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# RAIN GAIN NATIONAL OBSERVERS GROUP (NOG) MEETING, UK

London, 29<sup>th</sup> February 2012



# CONTENTS

1. Agenda for the day
2. Introduction to the RainGain project – Marie-Claire ten Veldhuis
3. The role of the UK partners in the RainGain Project
  - 3.1. The UK Met Office – Timothy Darlington
  - 3.2. Imperial College London – Čedo Maksimović
  - 3.3. Local Government Flood Forum – Laurie Thraves
4. Wrap-up, questions

# 1. AGENDA FOR THE DAY

- 10:00 – 11:00: Introduction to the RAINGAIN project (RainGain partners)
- 11:00 – 12: Presentations
  - Louise Clancy (Greater London Authority)
  - Stephen Merrett (Environment Agency)
  - David Lees (Defra)
- 12:00 – 13:00: Lunch
- 13:00 – 14:00: Break-out:
  - Rainfall as an input for urban pluvial flood modelling and forecasting (Chair: Malcolm Kitchen – Met Office)
  - Hydrological/hydraulic models for urban pluvial flooding and forecasting (Chair : Čedo Maksimovic - ICL)
  - Improved management of urban pluvial flooding (Chair: Laurie Thraves – LGFF)
- 14:00 – 14:30: Coffee break
- 14:30 – 16:00: Summary / Conclusions
  - Report from break-out session (3 x 10 min)
  - Discussion (15 min)
  - Conclusions and close (10 min)



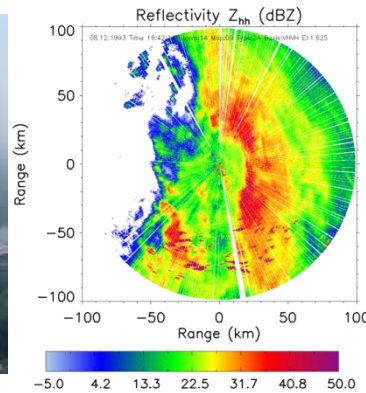
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## 2. INTRODUCTION TO THE RAINGAIN PROJECT

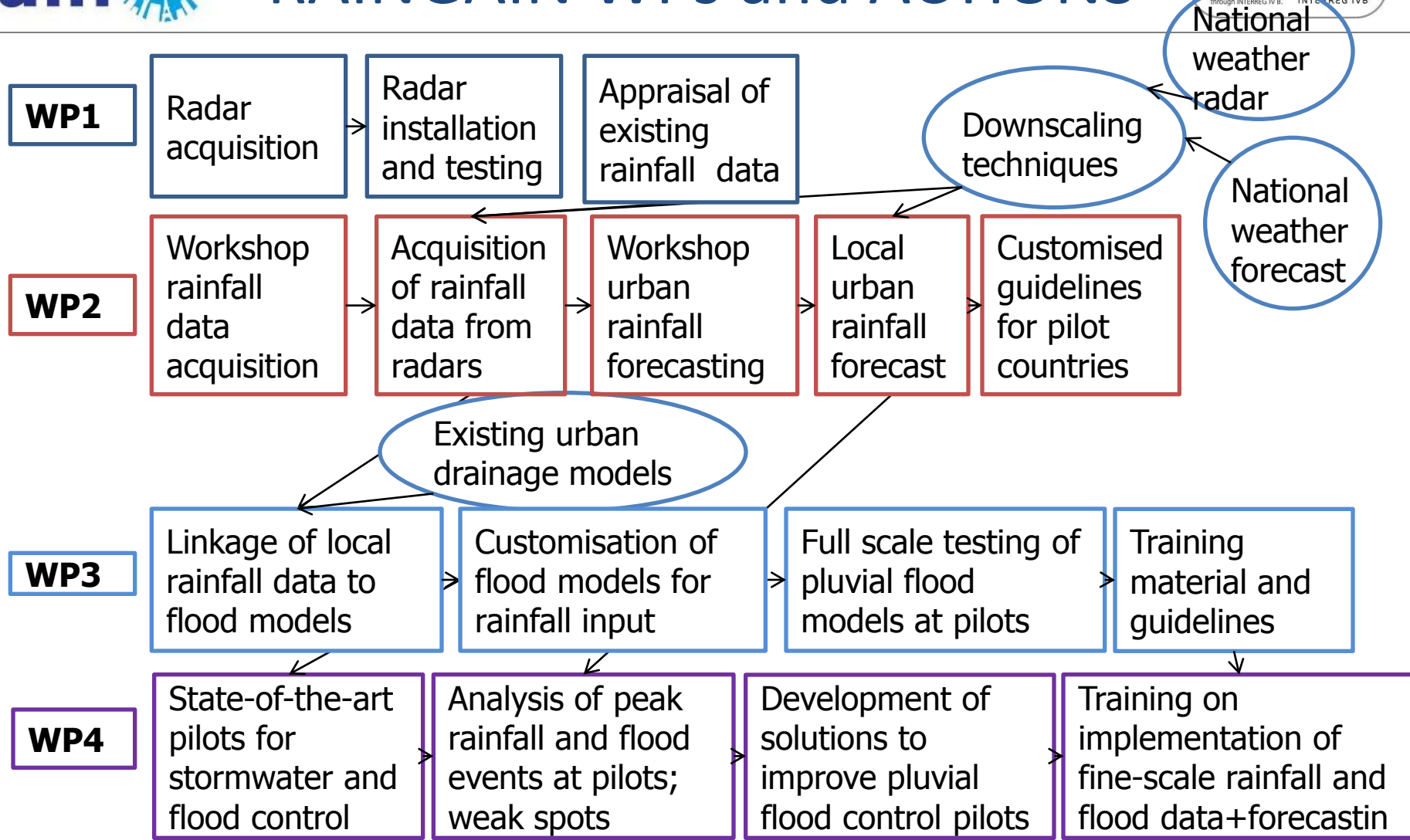
Marie-Claire ten Veldhuis



## RAINGAIN – Project Objective

**Objective:** to improve fine-scale measurement and prediction of rainfall and to enhance urban pluvial flood prediction in order to enable urban water managers to adequately cope with intense storms, so that the vulnerability of populations and critical infrastructure can be reduced.





# RAINGAIN WP1

**WP1**

A1 Radar acquisition

A2 Radar installation and testing

A3 Appraisal of existing rainfall data

A4 Future use and ownership of radar

Output:  
Radars NL,  
F

Output:  
report on  
testing

Output:  
presentations at  
pilots (Nat Obs  
Groups)

Output:  
agreement with  
future owner  
(NL)



# RAINGAIN WP2

**WP2**

**A5**  
Workshop  
rainfall data  
acquisition

Output:  
methods for  
fine-scale  
rainfall  
measurement

**A6**  
Acquisition  
of rainfall  
data from  
radars

Output:  
Rainfall  
estimates  
for pilots

**A7** Workshop  
urban rainfall  
forecasting

Output:  
method for  
fine-scale  
rainfall  
prediction

**A8** Local  
urban  
rainfall  
forecast

Output:  
technology  
for fine-  
scale  
rainfall  
prediction  
in pilots

**A9**  
Customis  
ed  
guidelin  
es  
for pilots

Guideline  
s+  
training  
material  
for pilot  
countries





# RAINGAIN WP3

Existing urban drainage models

WP3

A10 Linkage of local rainfall data to flood models

Output: platform for automatic linkage

A11 Customisation of flood models for rainfall input

Output: Customised flood models for pilots

A12 Full scale testing of pluvial flood models at pilot locations

Output: tested and implemented flood models for pilots + reports

A13 Training material and guidelines

Output: Training material and guidelines for pilots



# RAINGAIN WP4

A14 State-of-the-art pilots for stormwater and flood control

A15 Analysis of peak rainfall and flood events at pilot locations; weak spots

A16 Development of solutions to improve pluvial flood control at pilots

A17 Training on implementation of fine-scale rainfall and flood data and forecasting in water mgt. practice

## WP4

Output: Report current flood control in pilots

Output: List of flood-prone locations, flood causes and characteristics

Output: Customised solutions for flood-prone locations at pilots + test results

Output: Training material, manuals, guidelines for implementation



# Project management and WP Leaders

Project coordinator: scientific content

Marie-claire ten Veldhuis

Project management: financial and administrative procedures

Alwin Wink, Regina Edoó

WP1: Installation and testing of radars

Lead: ParisTech, Daniel Schertzer

WP2: Fine-scale rainfall data acquisition and prediction

Lead: KU Leuven, Patrick Willems

WP3: Urban pluvial flood modelling and prediction

Lead: Imperial College of London, Cedo Maksimovic

WP4: Implementation of fine-scale rainfall data, flood modelling and prediction into urban water management practice

Lead: TU Delft, Marie-claire ten Veldhuis



# RAINGAIN: 13 Partners

- 1) TU Delft (NL)
- 2) Zuid-Holland Province (NL)
- 3) Gemeentewerken Rotterdam (NL)
- 4) KU Leuven (B)
- 5) Aquafin NV (B)
- 6) Ecole des Ponts ParisTech (F)
- 7) Marne-la-Vallée (F)
- 8) Seine-St.-Denis (F)
- 9) Météo France (F)
- 10) Imperial College London (UK)
- 11) Met Office (UK)
- 12) Local Government Flood Forum (UK)
- 13) Véolia (F)

## 4 Pilots:

Rotterdam (NL)

Leuven (B)

Marne-la-Vallée (F)  
Seine-St.-Denis (F)

Croydon (UK)  
Redbridge (UK)



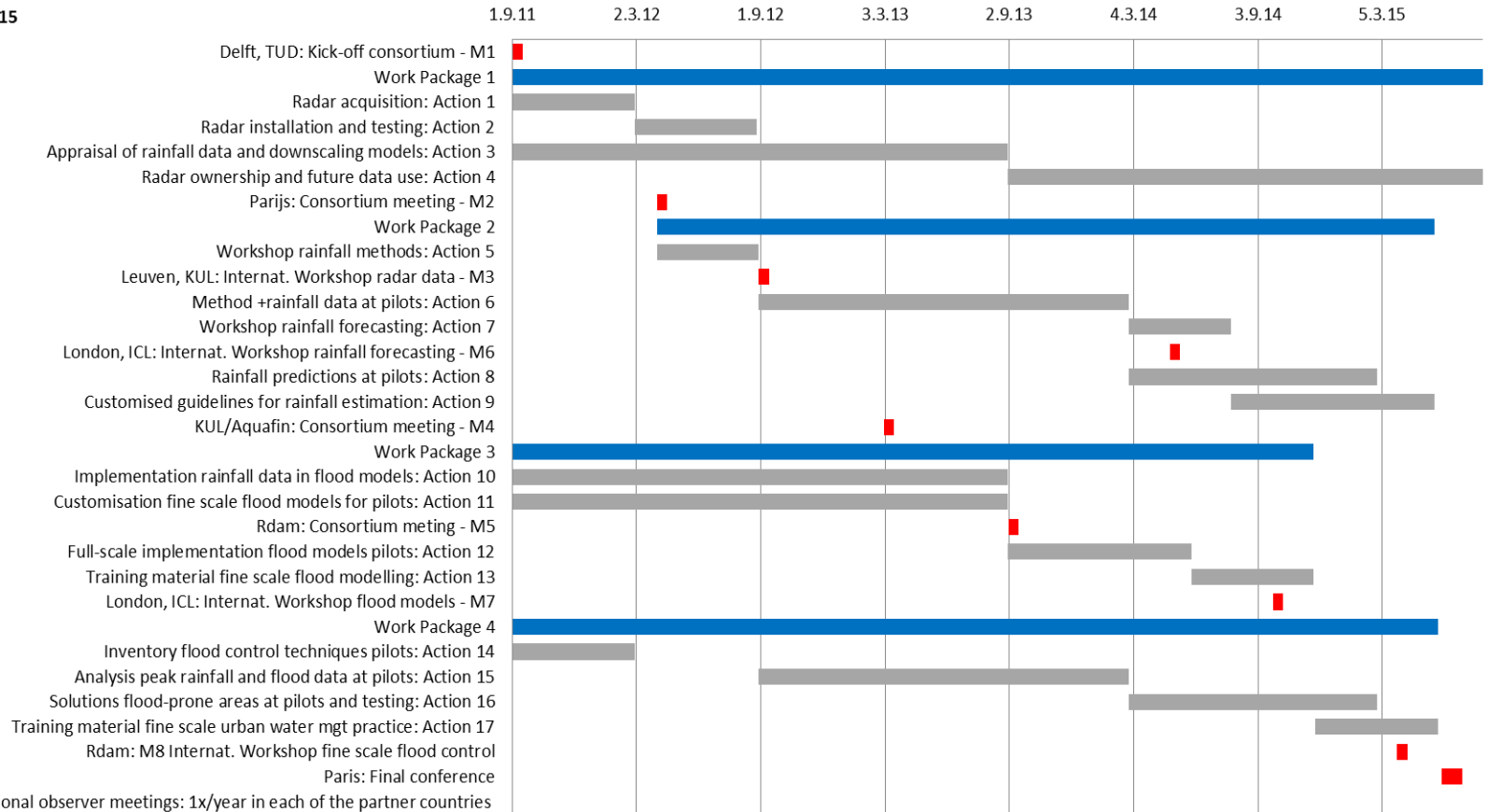
## RAINGAIN – 13 partners in cooperation

- Knowledge exchange between partners
- Field visits pilot locations
- Workshops on development of common methods and training for practical application
- Demonstrations of tools (radar, flood model), applications (radar results, model results), solutions (early warning systems, operational control, storage basins) to other partners



# Planning

Start date: 1 Sep 2011  
End data: 31 July 2015



Start date: 1 September 2011  
End date: 31 July 2015

Pre-Kickoff:  
29-30 Aug 2011

Official Kickoff: 17-18 Nov 2011

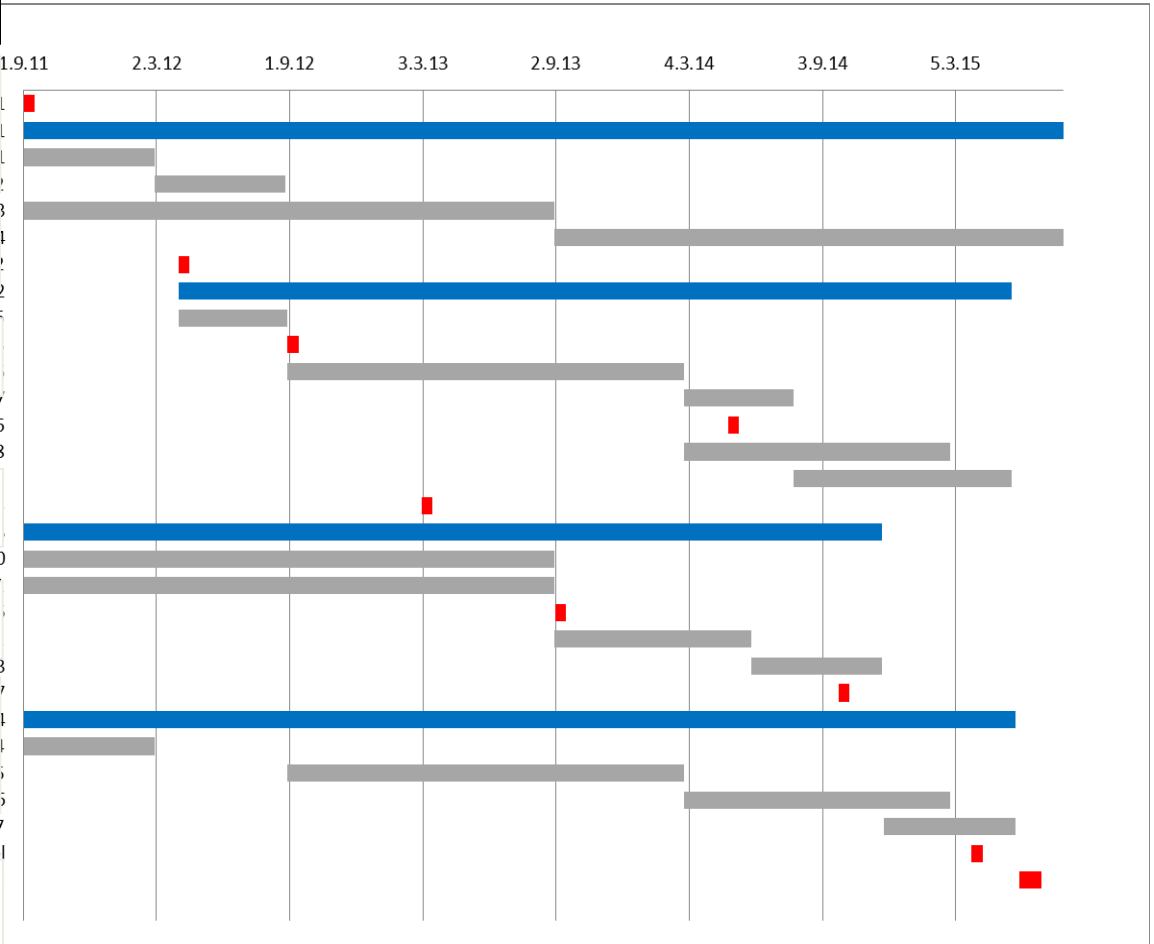
Project consortium meetings

Workshops for WPs

Small Technical meetings

Nat. Observer Group meetings:  
4 per pilot/country

International conference: June  
2015









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# 3. THE ROLE OF THE UK PARTNERS IN THE RAINGAIN PROJECT

3.1. The UK Met Office – Timothy Darlington

3.2. Imperial College London – Čedo Maksimović

3.3. Local Government Flood Forum – Laurie Thraves





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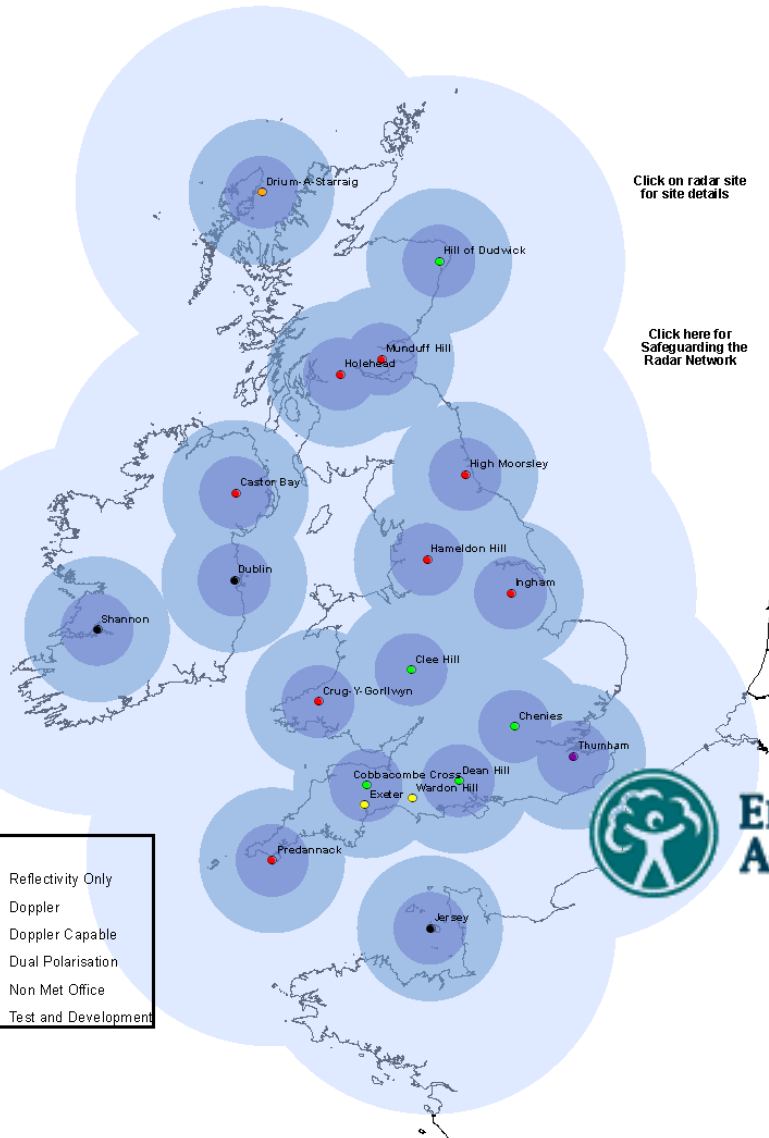
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# 3.1. THE UK MET OFFICE

Timothy Darlington



## UK Weather Radar Network



Click on radar site for site details

Click here for Safeguarding the Radar Network

Key	
<span style="color: red;">●</span>	Reflectivity Only
<span style="color: green;">●</span>	Doppler
<span style="color: orange;">●</span>	Doppler Capable
<span style="color: purple;">●</span>	Dual Polarisation
<span style="color: black;">●</span>	Non Met Office
<span style="color: yellow;">●</span>	Test and Development

- Location of radars
- 5km resolution coverage
- 2km resolution coverage
- 1km resolution coverage

• A diverse range of stakeholders and users



- C-Band Siemens-Plessey Radars
  - Oldest ~ 30 years old
  - Mechanically sound but control systems & transmitters increasingly facing obsolescence issues
- Renewal project installing new modern Motors, Drive systems and Transmitters – keeping pedestals and antennas – upgraded to Dual Polarization
- In-house signal processing and control system
  - Cyclops
    - Currently 14 bit ADC @ 100MHz
    - Upgrading to 16 bit ADC @ 200MHz
    - Allows access to whole of signal processing chain



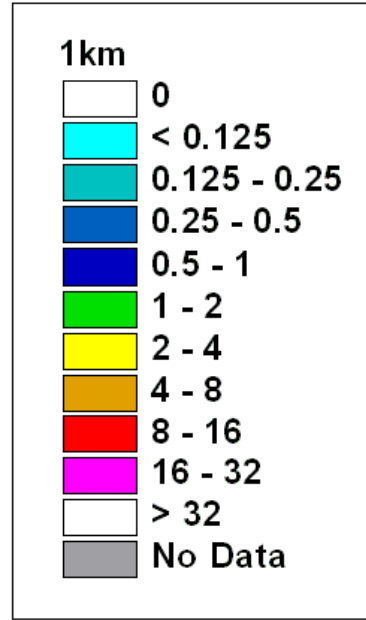
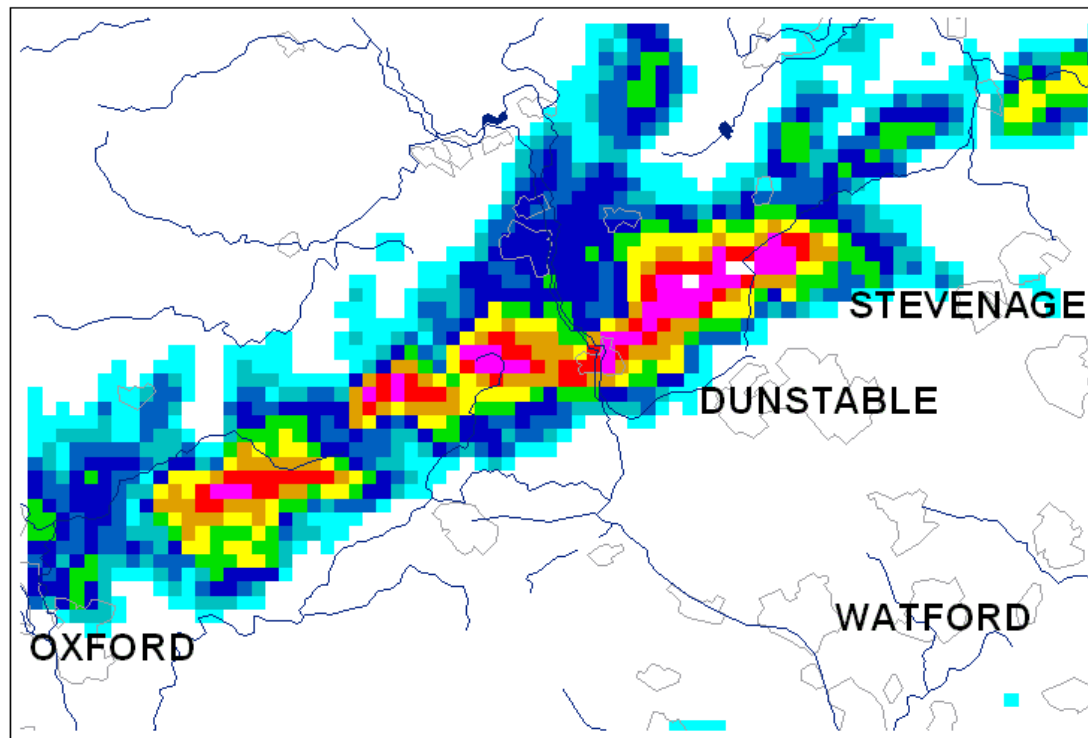
## Research focus:

# Improving rainfall estimates for hydrological modelling using conventional weather radars

- Improved Spatial resolution
- Improved Temporal resolution
- Improved target type discrimination / quality control
- Improved gauge merging scheme

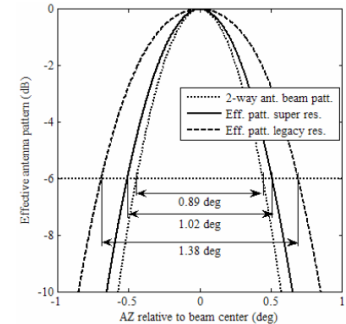


Chenies 1km radar data



- Azimuthal Resolution

- Beam width usually degraded by scanning motion of antenna
- Sharpen beam by applying suitable weighting function



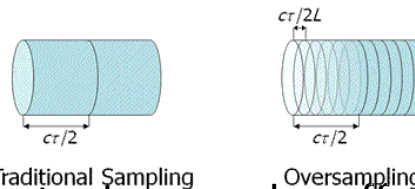
- Range resolution

- Oversample data and process to de-convolve effects of transmitter pulse and receiver

- Can be used to increase range resolution

Or

- Can be used to increase number of independent samples available to reduce measurement variance in averaging stage
  - Scan speed could then be increased with reduced degradation of measurement error



# Expected Benefits of Improved Temporal Resolution



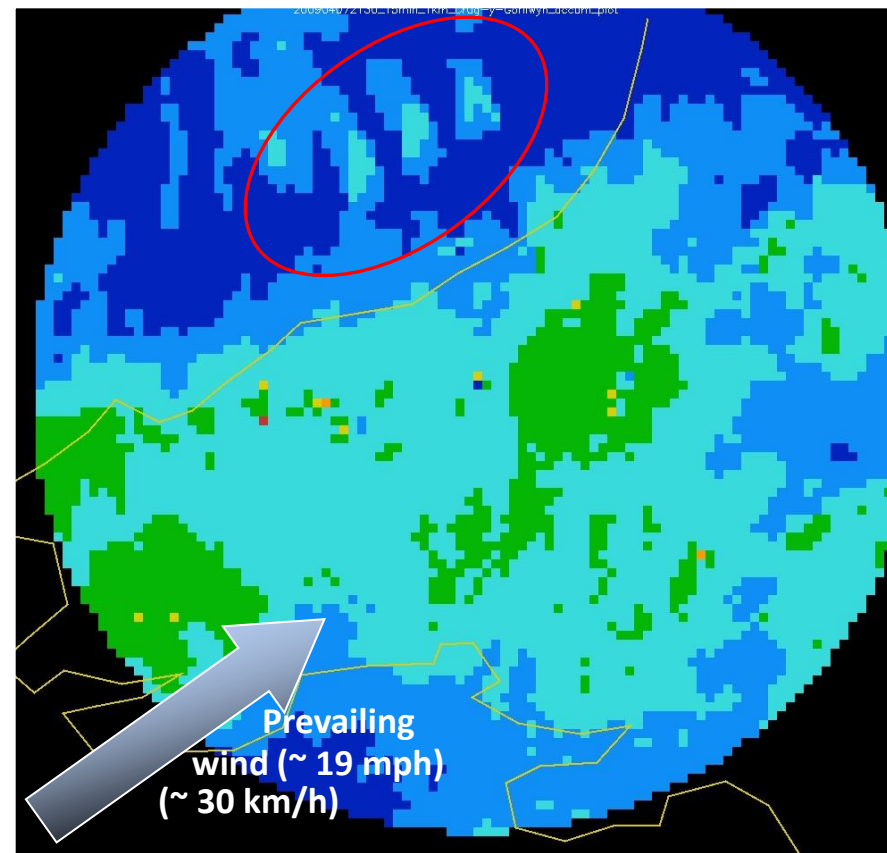
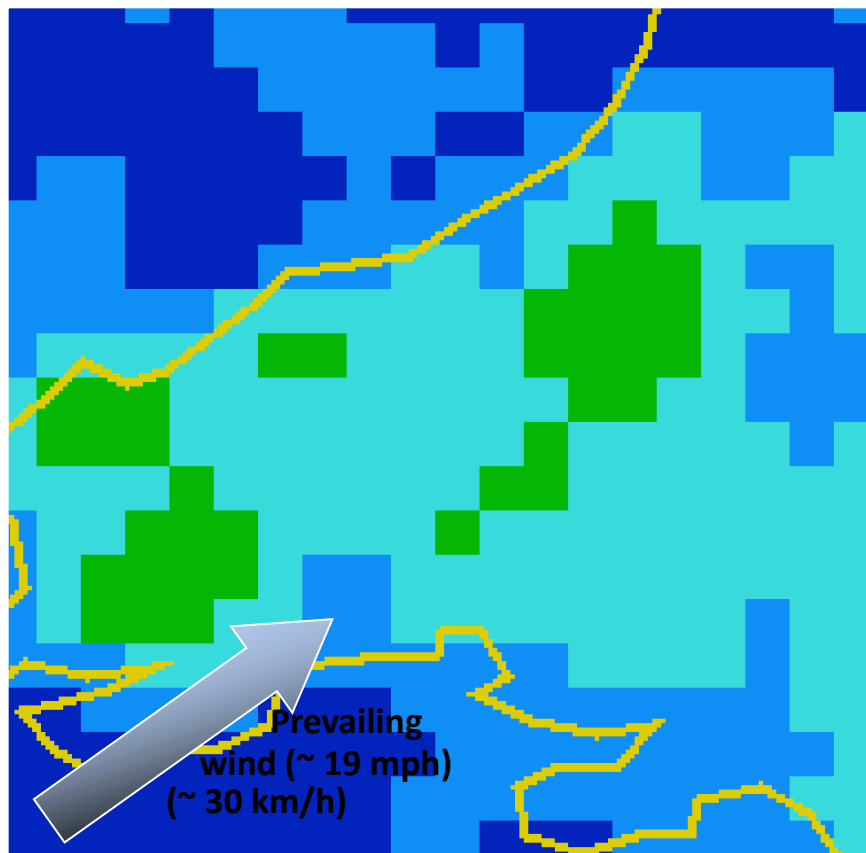


- Different users place different (and increasing!) demands on weather radar time resources
- Hydrological users want best rainfall estimate
- NWP community want Volume Reflectivity, Radial Velocity and relative humidity
- Forecasters want a combination of the two



# A problem of spatio-temporal resolution

15 min accumulation for Crug-y-Gorllwyn

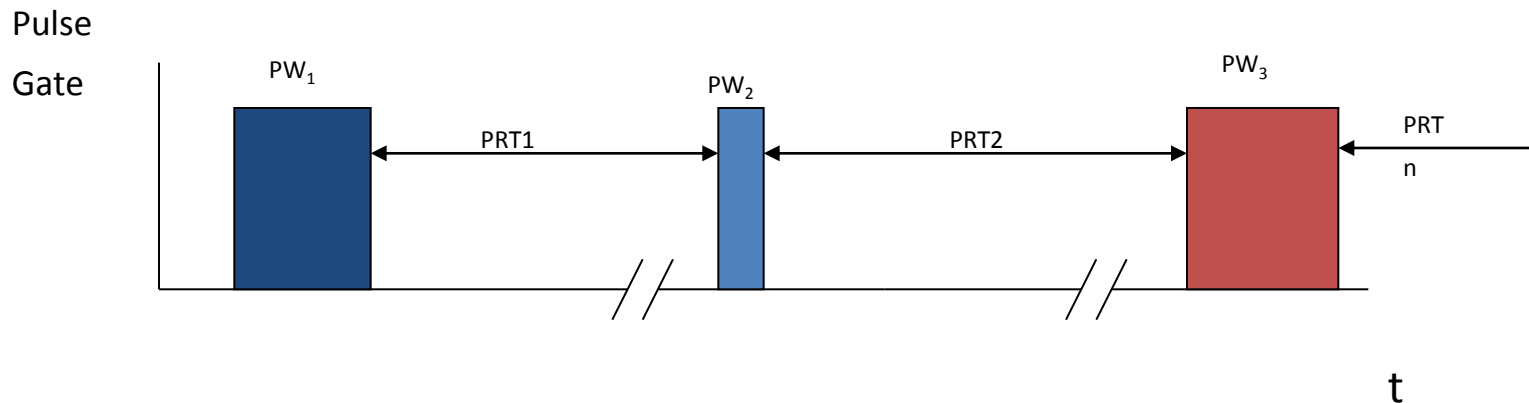


# Threshold wind velocities for stroboscopic banding to occur

- 5 km radar resolution
  - 60 km/h (~ 37 mph, ~ 32 knots) – Rarely observed.
- 2 km radar resolution
  - 24 km/h (~ 15 mph, ~ 13 knots) – Observed fairly frequently and sometimes causes banding.
- 1 km radar resolution
  - 12 km/h (~ 7.5 mph, ~ 6 knots) – Regularly observable and frequently causes pixel jumping even in non-extreme precipitation events.



- New Transmitter has novel control interface
  - Trigger pulse from DSP controls pulse length and repetition frequency simultaneously
  - Possibility of Mixed pulse lengths and PRFs



- Can we use this to maximise transmitted power (for best reflectivity) at same time as having high PRF (for best Doppler) within the duty cycle of the Tx?
- Take advantage of the fact that the rain does not fully de-correlate between pulses



The aim is to recommend and implement the most appropriate method for merging gauge and radar data and to produce a real time 15 minute gauge radar merged rain accumulation product at 1km resolution.

## Key stages:

- Develop a real time gauge QC system suitable for use with MO and EA gauge data
- Design, develop and evaluate the merging technique.

The merged accumulation product will be used:

- As input to the G2G rainfall runoff model (key input is a 15 minute accumulation).
- As “ground truth” for near-real-time verification of STEPS and NWP precipitation forecasts
- As an hourly rainfall accumulation input to the UKPP-MOSES-PDM: improving on the current use of hourly radar rainfall accumulations.
- As information for forecasters' guidance, using a range of accumulation periods.



# Goals

- Currently producing 500m composite over London
  - Determine limits of this with current C band hardware
- Decrease current volume scan times by factor of two
- Maintain operational network with diverse user requirements
- Share information on the relative merits of X and C band radars





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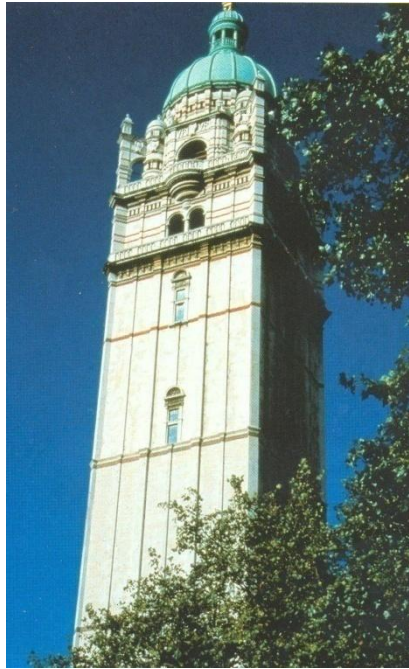
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## 3.2. IMPERIAL COLLEGE LONDON

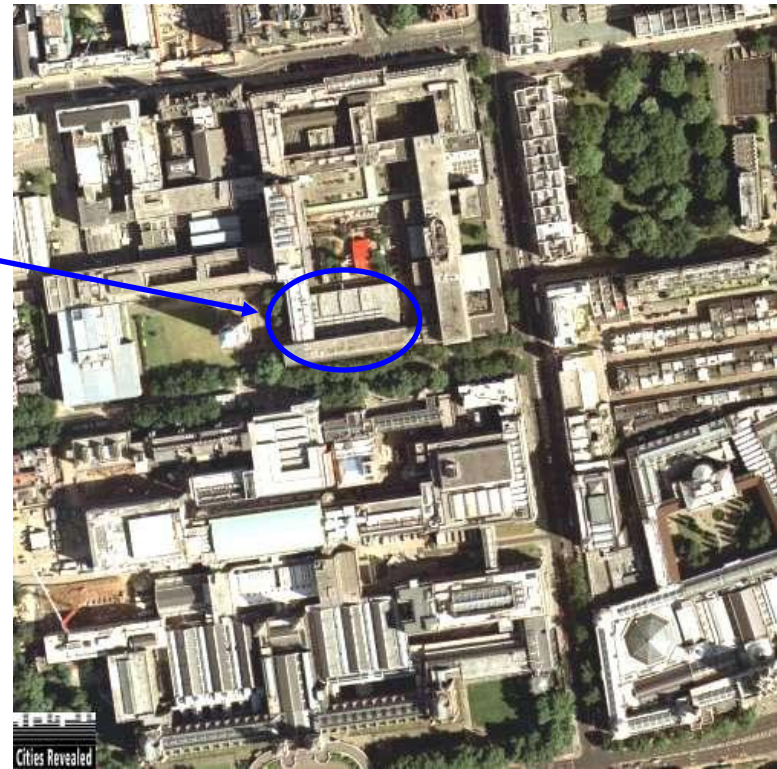
Čedo Maksimović



# Environmental and Water Resource Engineering (EWRE) at Imperial College London

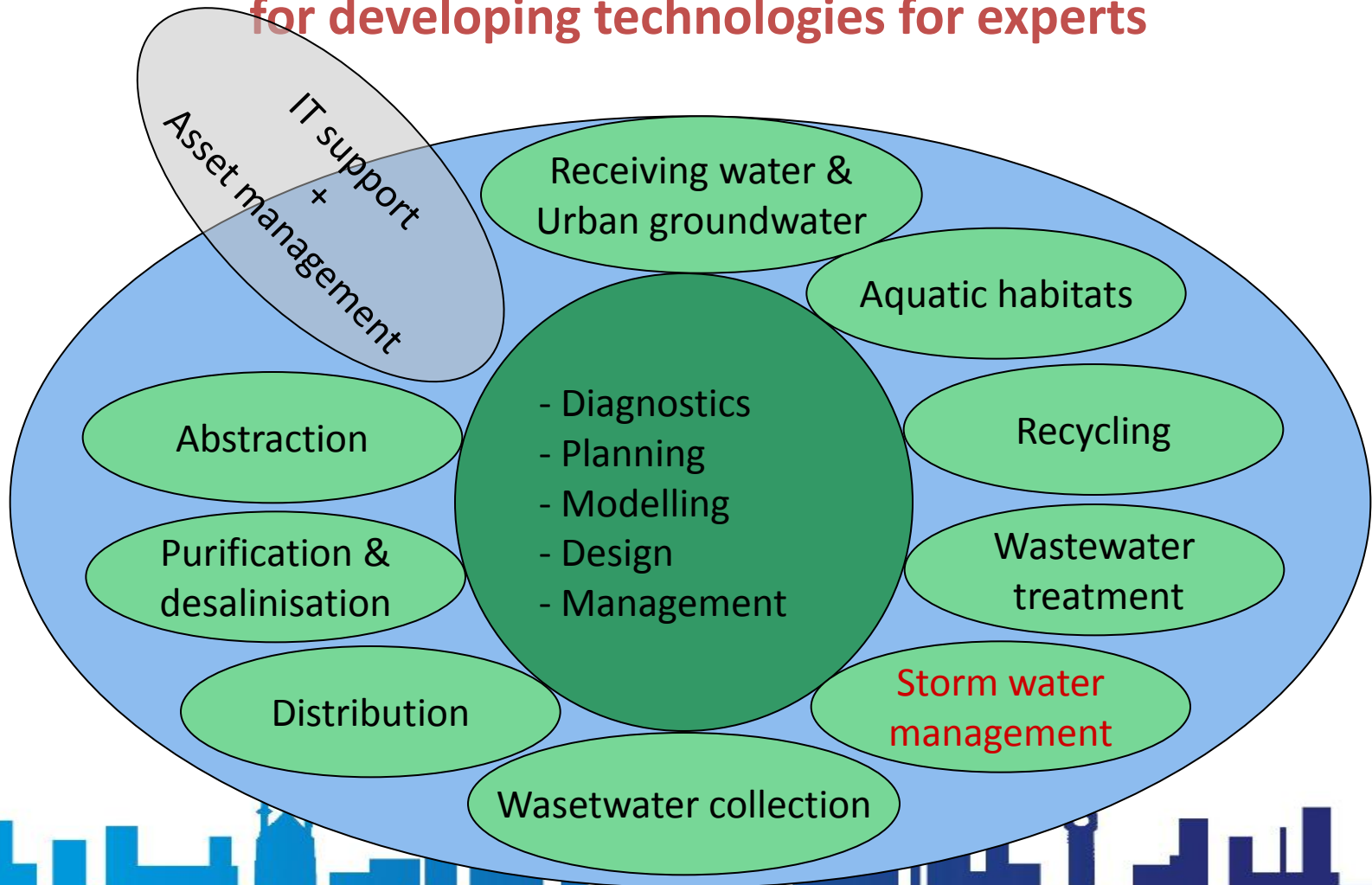


Department of  
Civil &  
Environmental  
Engineering





For solving local problems and  
for developing technologies for experts



# Urban Pluvial Flooding

**Extreme rainfall events exceed the capacity of the drainage system!**



## Urban Pluvial Flooding

- Poor drainage capacity of minor (sewer) system
- Surface flow (major system)
- Dynamic interactions (exchange of mass) between the two systems
- Everything happens quickly – “flash floods”



## Urban Pluvial Flooding

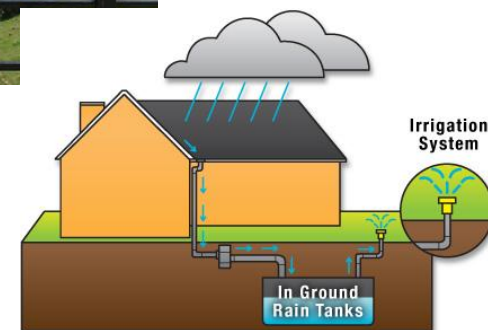
# Mitigation solutions?

WP3

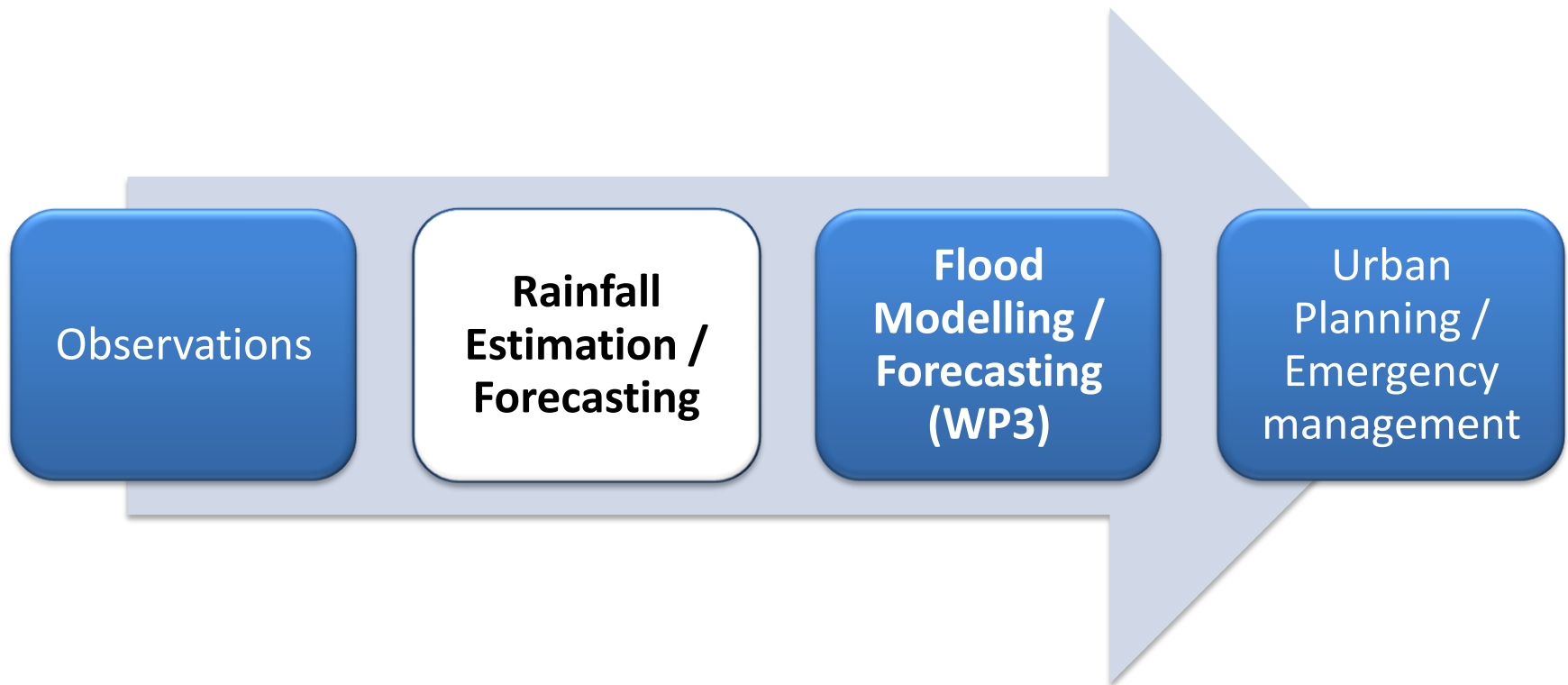
Improved Forecasting and Event Management

WP4

Advanced (Water Sensitive) Urban Planning + Improved Management

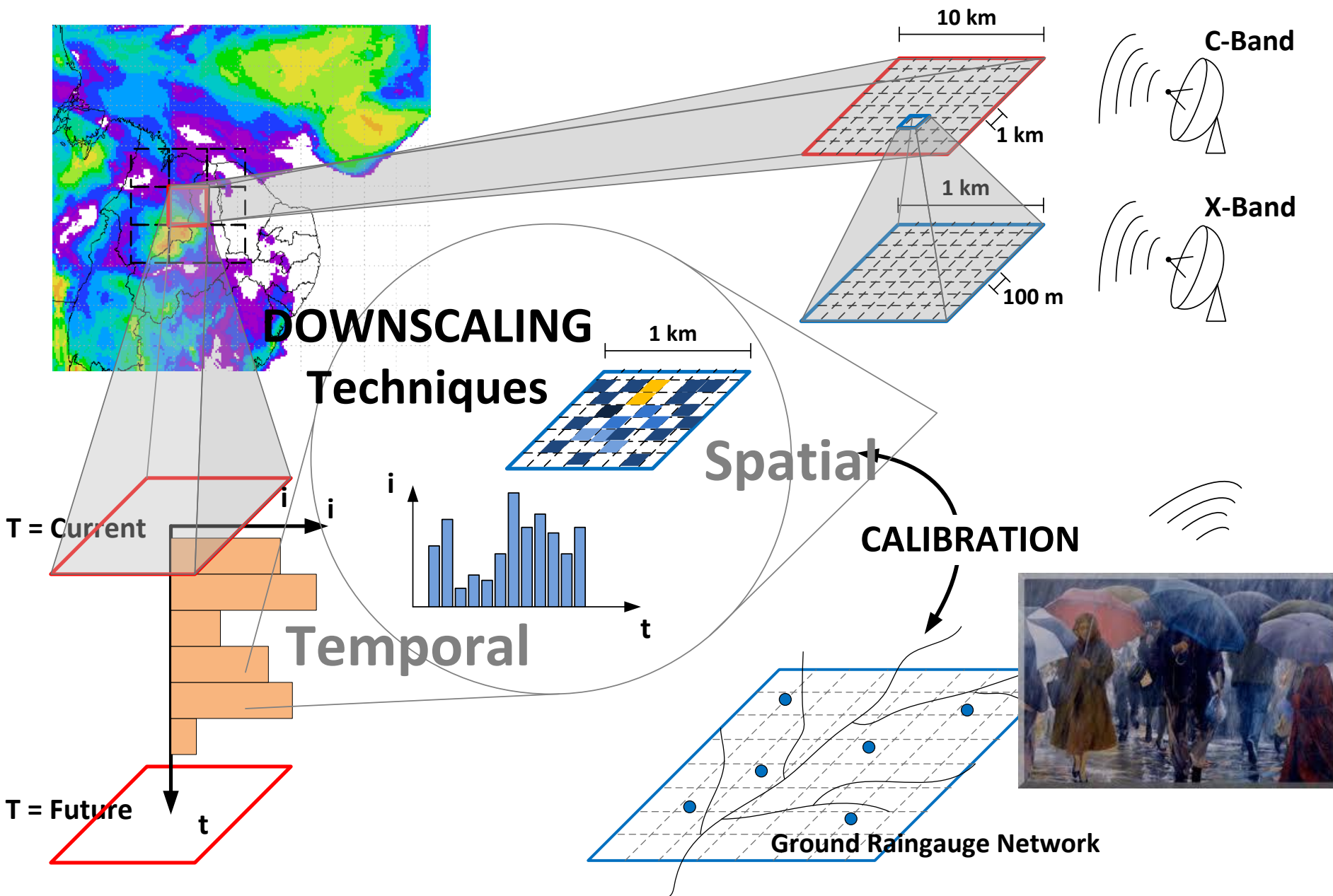


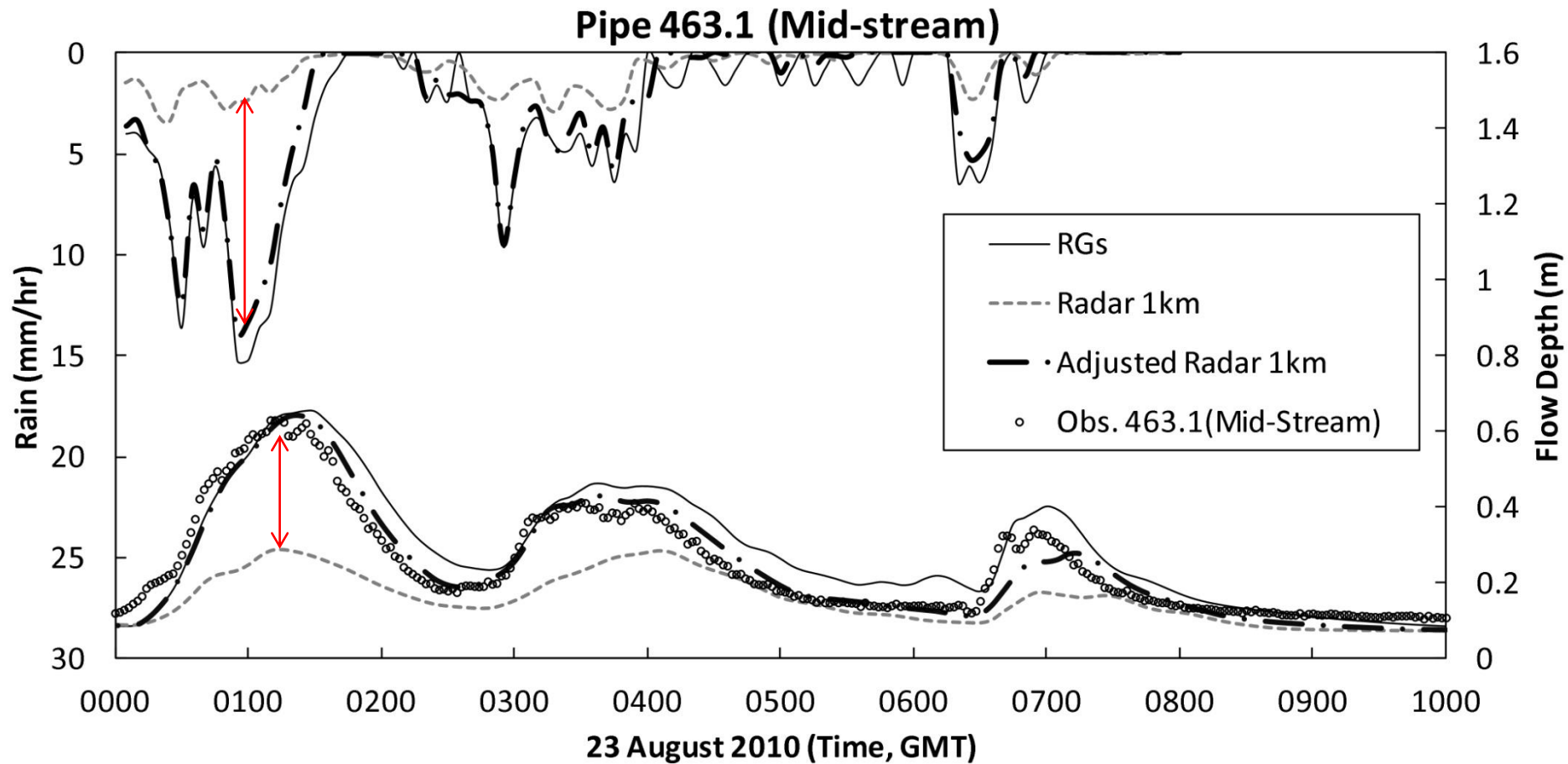
## Model Assembly for Pluvial Flood Modelling, Forecasting and Management

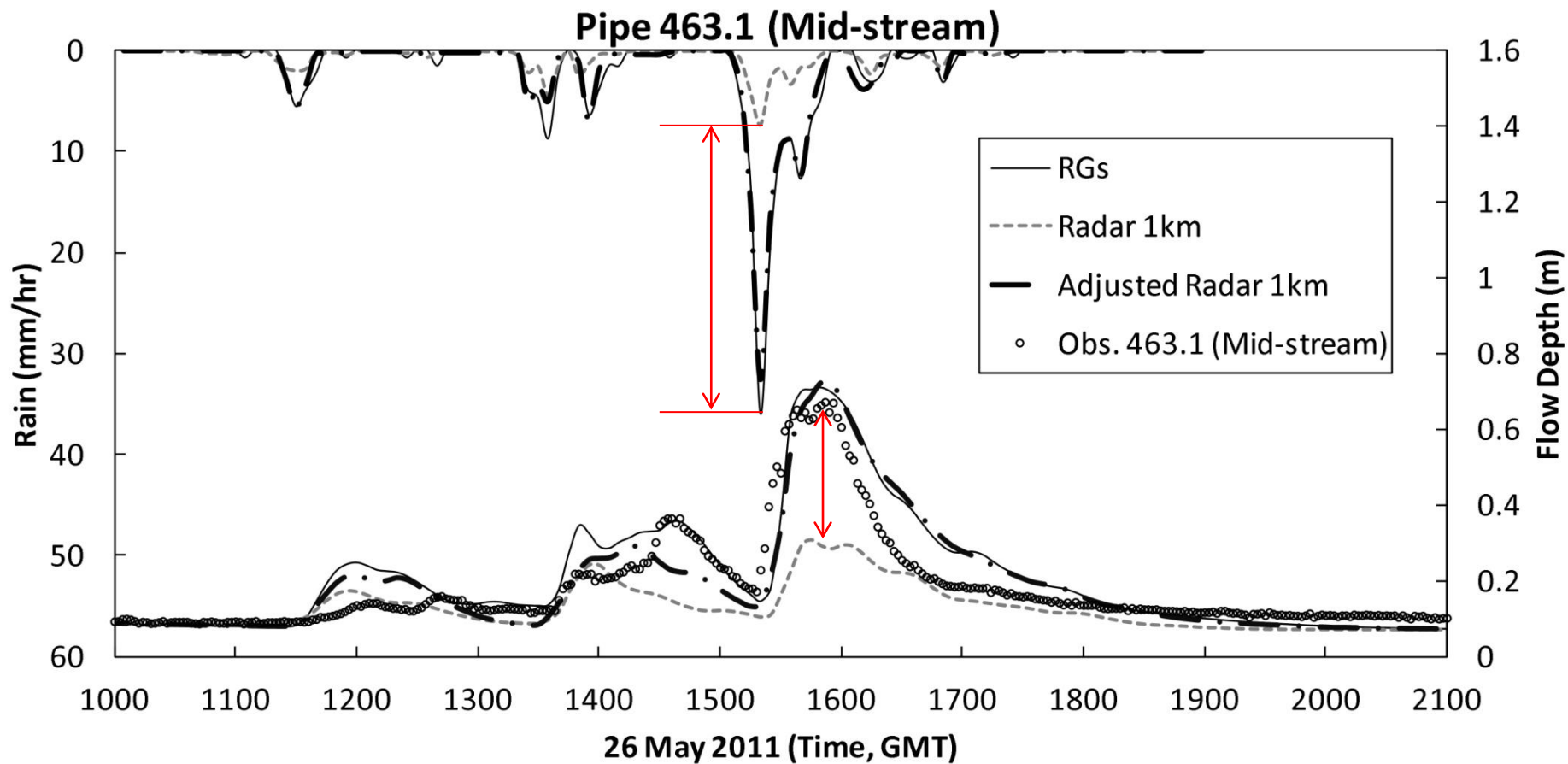


# Numerical Weather Prediction: UM/MM5

# NOWCASTING



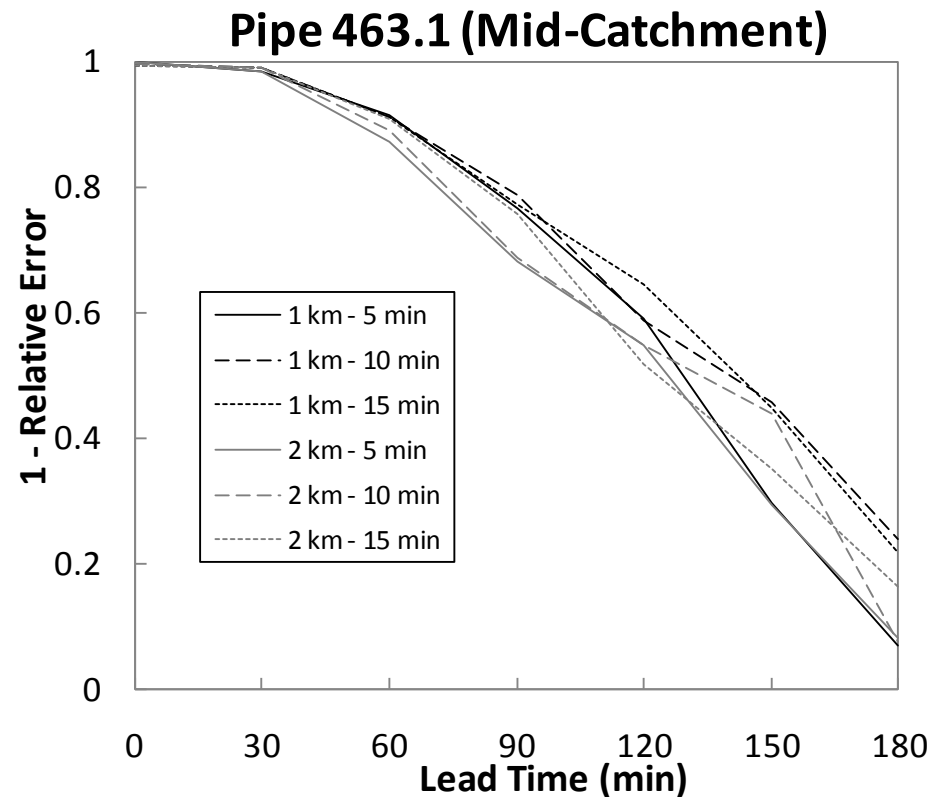




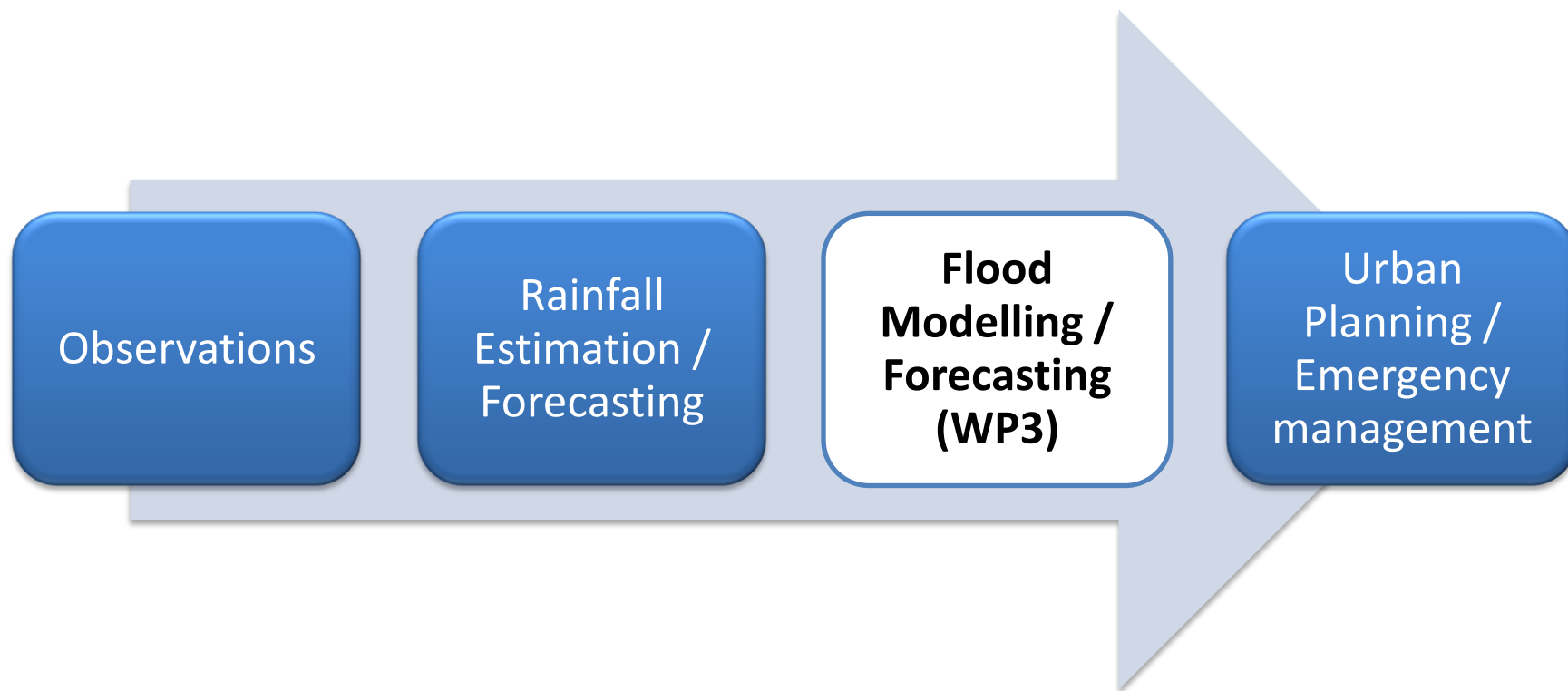


$$1 - \text{Relative Error} = 1 - \left\langle \frac{|Y_{\text{Nowcast}} - Y_{\text{Nimrod}}|}{Y_{\text{Nimrod}}} \right\rangle$$

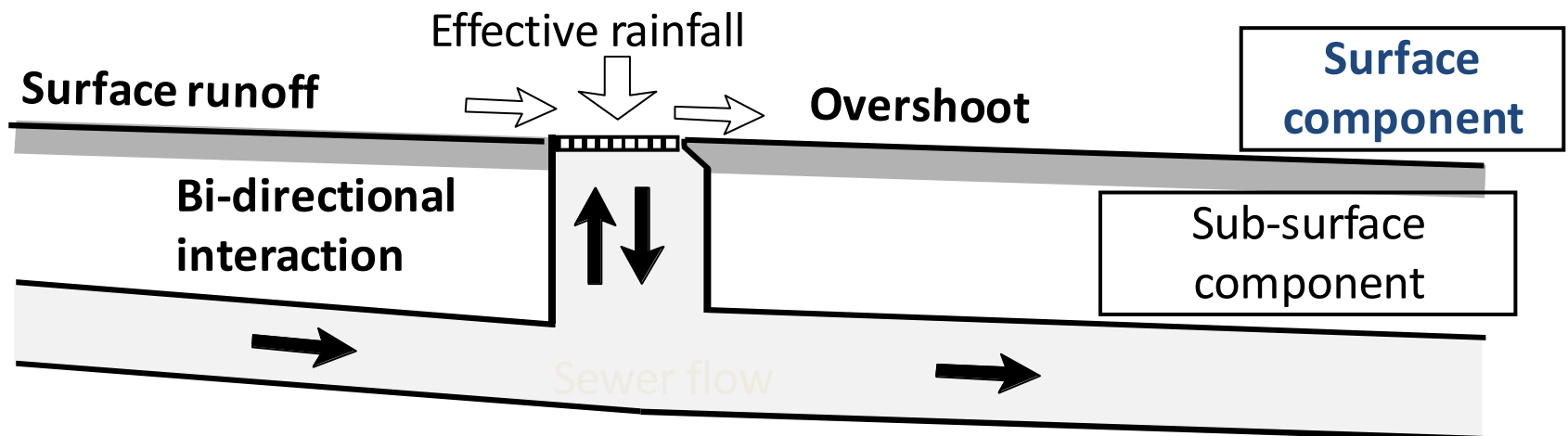
The results suggest that rainfall with finer resolution produces better results in flow estimates



## Model Assembly for Pluvial Flood Modelling, Forecasting and Management



# Modelling of Urban Pluvial Flooding – Dual Drainage Concept

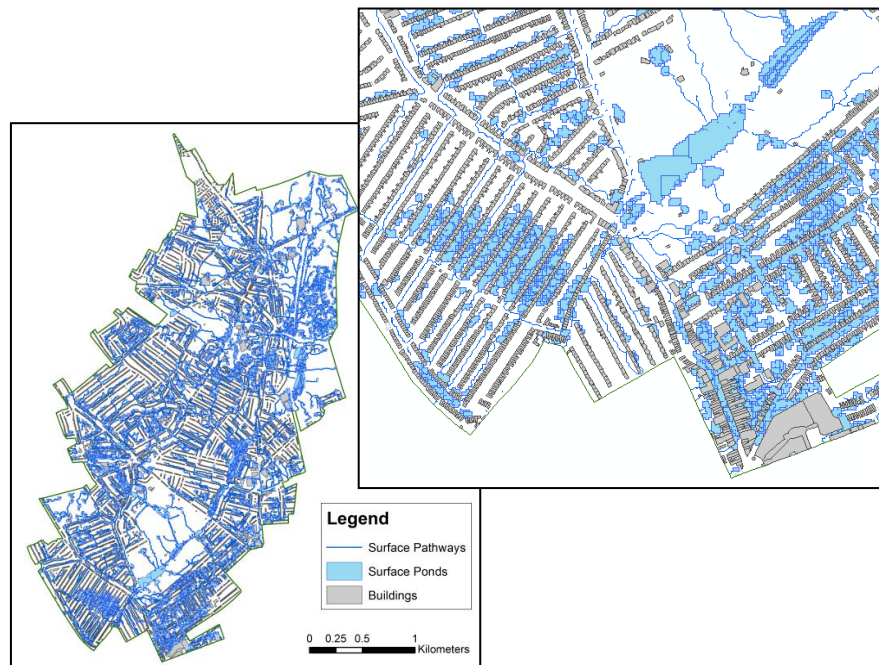


## Modelling of Urban Pluvial Flooding

### Dual-drainage concept: overland network + sewer network (1D)

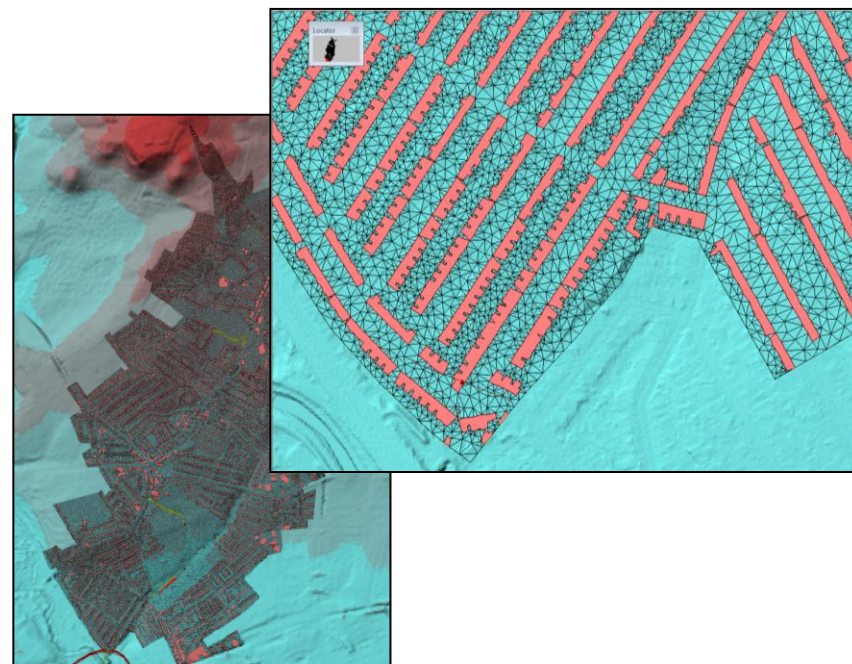
#### 1D overland flow modelling

Nodes (ponds) and links (flow paths)



#### 2D overland flow modelling

Surface divided into small elements (squares or irregular triangles)



# Modelling of Urban Pluvial Flooding

## Dual-drainage concept: overland network + sewer network (1D)

### 1D overland flow modelling

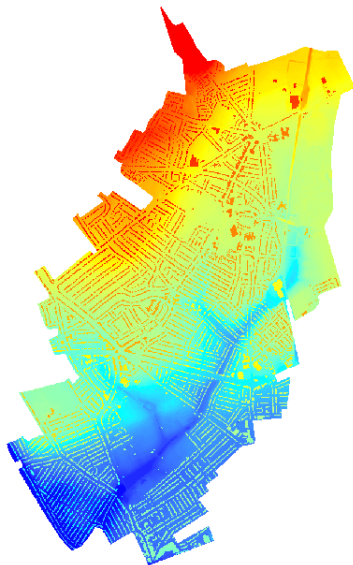
-Generated based on DEM

-Can be created manually (simplified, subjective and time consuming) or using the *AOFD tool* developed at Imperial College London

### 2D overland flow modelling

-Generated based on DEM

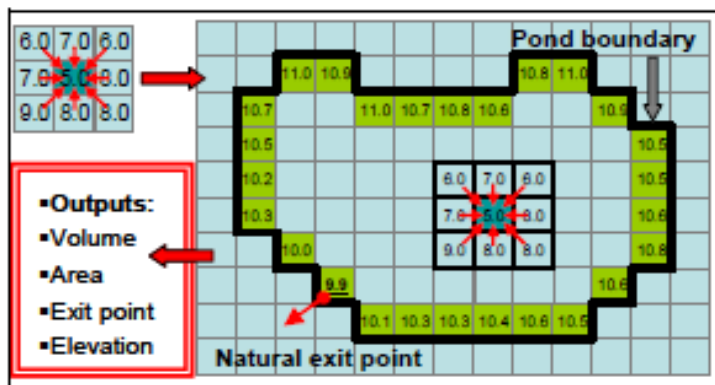
-Generated using routines available in commercial software packages



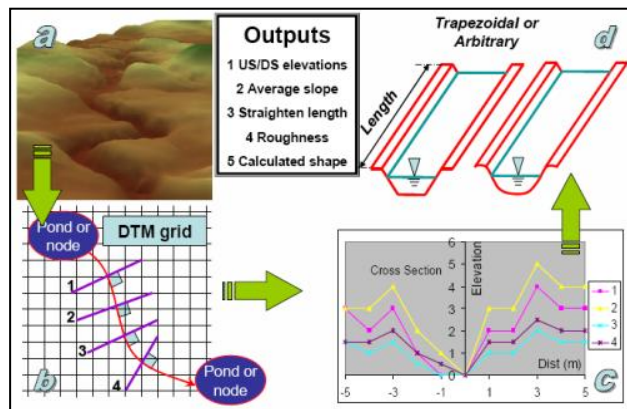
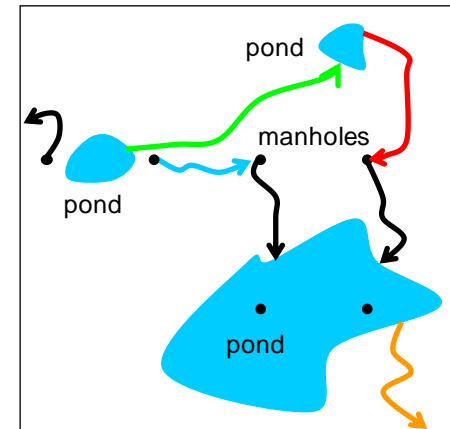
- Both overland models are based on DTM
- Quality of the DTM is critical (*desirable: 1 m horizontal resolution*)
- Airborne and terrestrial LiDAR

## Automatic Overland Flow Delineation (AOFD)

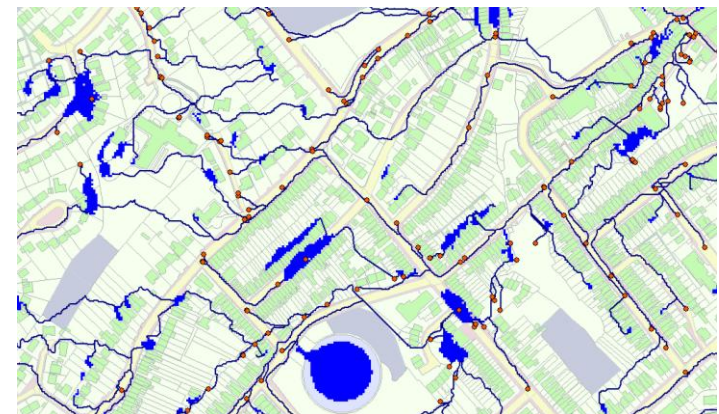
### 1. Pond delineation



### 2. Pathway delineation



### 3. pathways' geometry



### 4. 1D overland network

## Model Requirements

- **For urban pluvial flood modelling – planning purposes:**
  - Scenario/alternative analysis to support decision making
  - Very detailed models are required
  - Running time is not critical
  - **Input:** design storms, historical storms
  - **Output:** flow and level in pipes, flood extent and depth with fine resolution for different scenarios
- **For urban pluvial flood forecasting:**
  - Pluvial flooding is localised and happens quickly – detail and time are both critical!
  - **Input:** rainfall forecast with fine temporal and spatial resolution
  - **Output:** predicted flow and level in pipes, flood extent and depth with fine resolution
  - **Models must be fast** (to allow longer lead time and constant update of the prediction), **but also detailed!**

# 1D-1D Models vs. 1D-2D Models

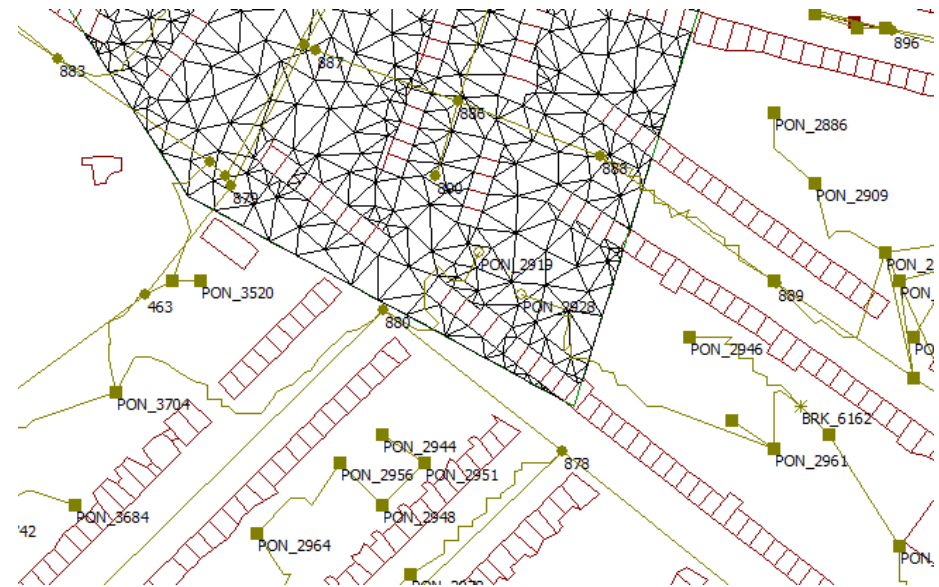
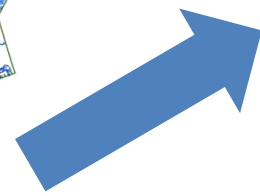
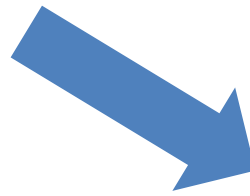
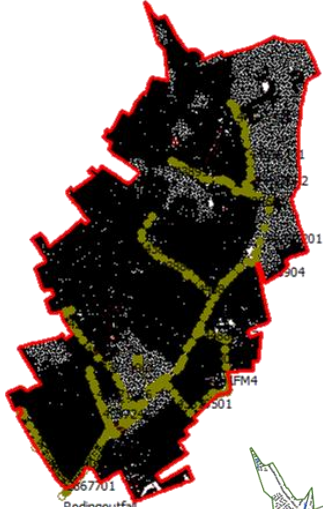
	1D-1D	1D-2D
Detail and Accuracy		✓
Computational time	✓	
Vizualization of results		✓





## To combine their advantages and overcome their disadvantages...

1D / 2D



**Hybrid**

**1D/1D + 1D/2D simulation**

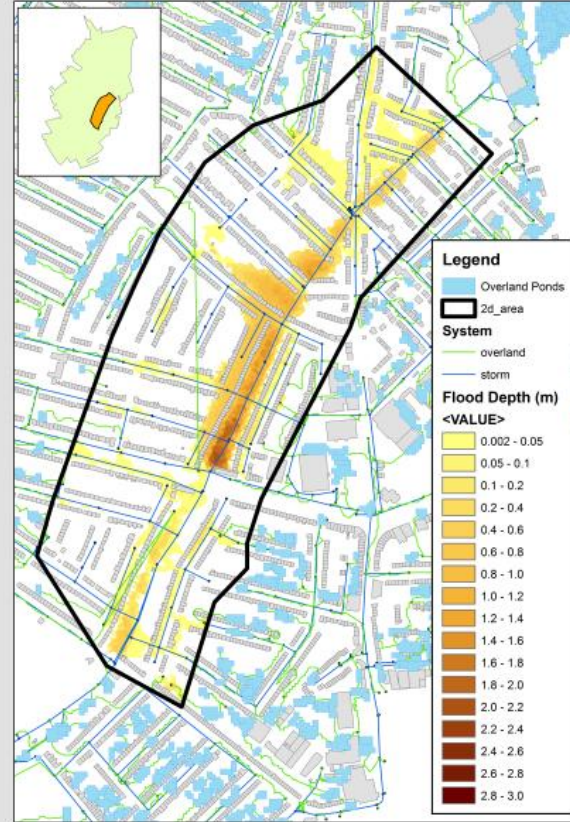
1D / 1D

## Do hybrid models perform well?

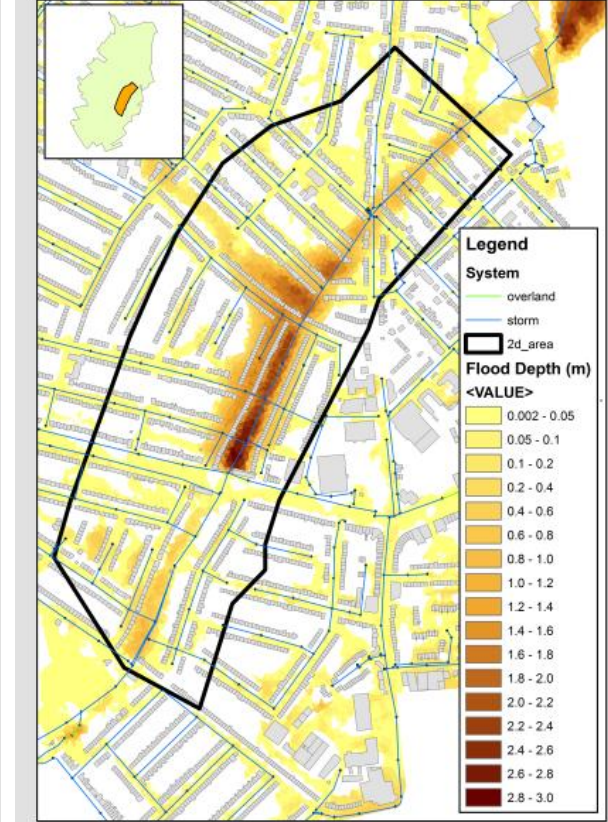
### 1D1D



### Hybrid



### 1D2D



## Simulation Time

Return Period	1D1D	Hybrid	1D2D
30 yr	01m 46s	04m 31s	45m 23s
100 yr	02m 11s	05m 20s	01h 11m 10s
200yr	04m 40s	05m 49s	01h 16m 05s

300 min event

**The new hybrid models can be almost as good as 1D-2D models but much faster!**



## WP3: Urban pluvial flood modelling and prediction

### Objective:

- To develop and test new methodologies, the associated software tools and application guidelines for short-term, fine scale, real-time pluvial (also called surface) flood **forecasting**.

### Outcome:

- Customised flood models to predict expected flood locations and flood depths in pilot locations based on rainfall data



## WP 3 - Actions

- **A10:** Adoption, customisation and automatic linkage of rainfall forecasts to pluvial flood models
- **A11:** Improvement and customisation of models for urban pluvial flood forecasting at fine scales in each of the pilot locations.
- **A12:** Full-scale testing of the models for pluvial flood prediction in each of the pilot locations
- **A13:** Development of guidelines and training material for capacity building and training of future end-users





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# 3.3. THE LOCAL GOVERNMENT FLOOD FORUM

Laurie Thraves





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## 4. WRAP UP, QUESTIONS



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