

Multifractal Predictability and Forecasts



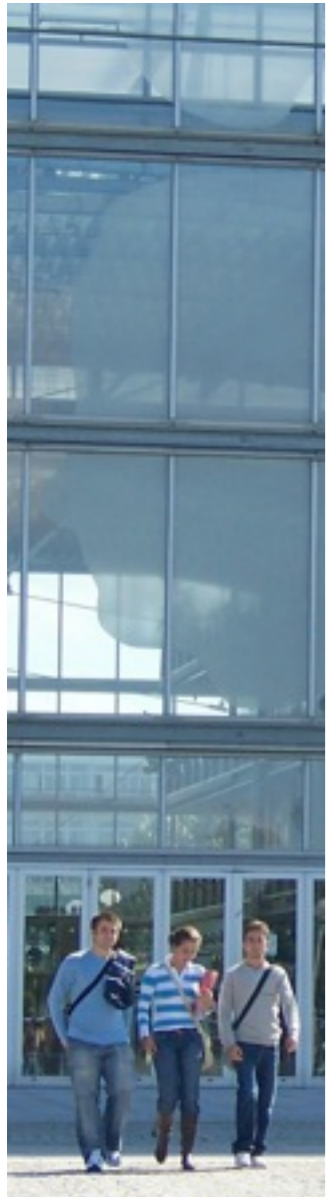
D. Schertzer
Ecole des Ponts ParisTech
U. Paris-Est

RainGain Workshop
Antwerpen, 31/03/2014

Predictability

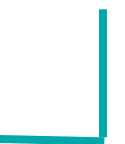


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- What can we predict?
 - What are the **intrinsic predictability limits**?
- Necessary to clarify what are they respectively for systems
 - complex only in time (ODE)
 - complex both **in space and time** (PDE)
- How to **reach these predictability limits**? (*)
 - (*) how to be “operational” without it?



Lessons from complexity in time?

- brought a wealth of striking results for (finite) nonlinear (ordinary) differential systems:

$$\underline{\dot{X}}(t) = \frac{d}{dt} \underline{X} = \underline{F}(\underline{X}, t)$$

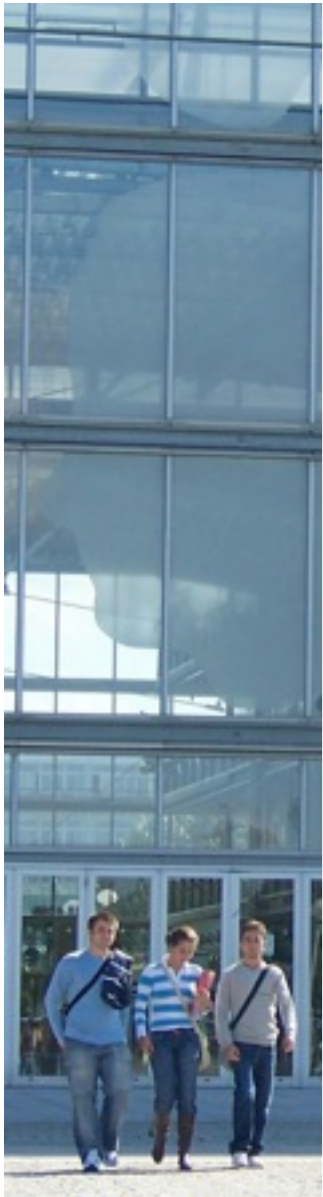
in a d -dimensional embedding space E_d

- or (simpler) iteration maps:

$$\underline{X}_{n+1} = \underline{G}(\underline{X}_n)$$



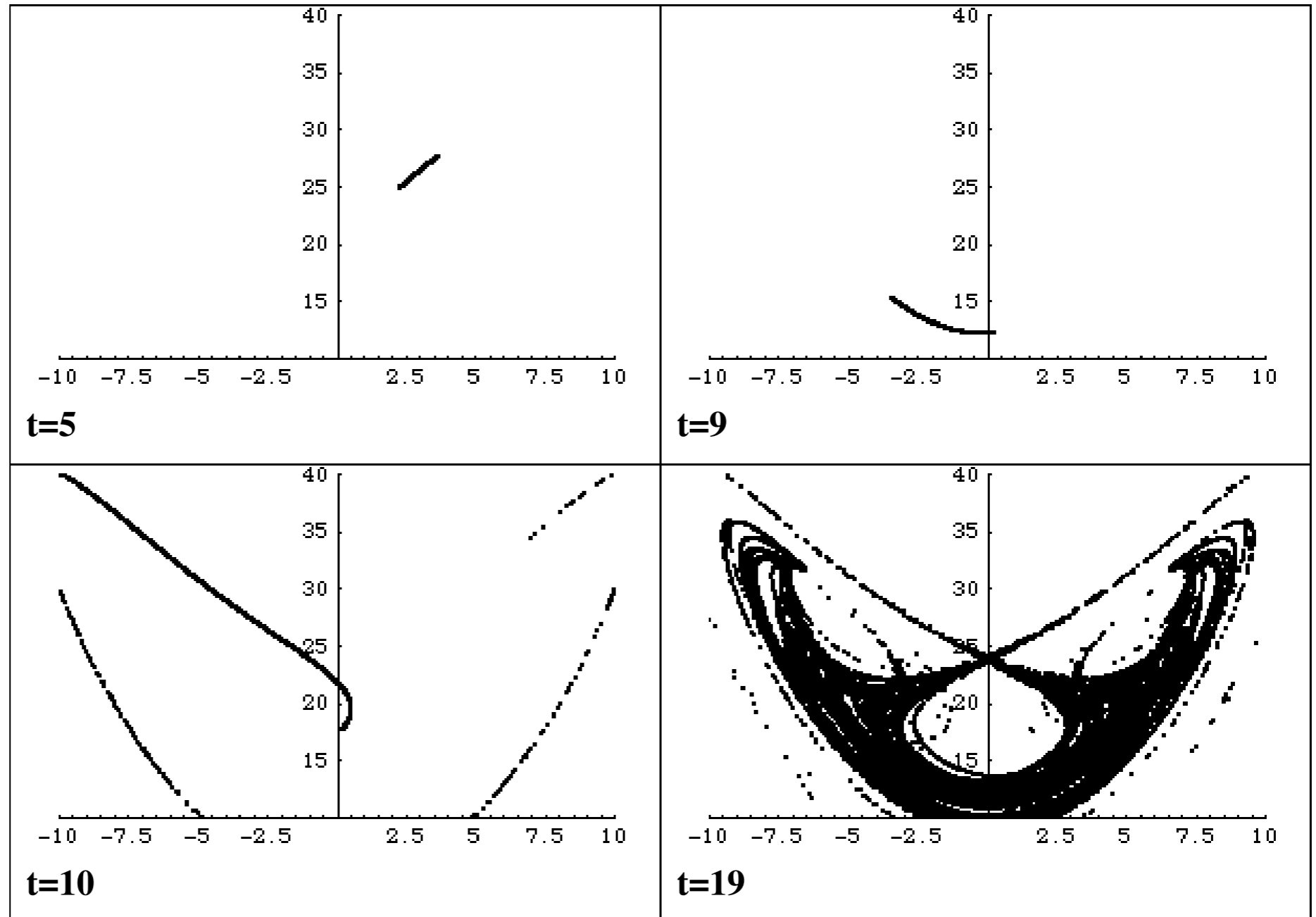
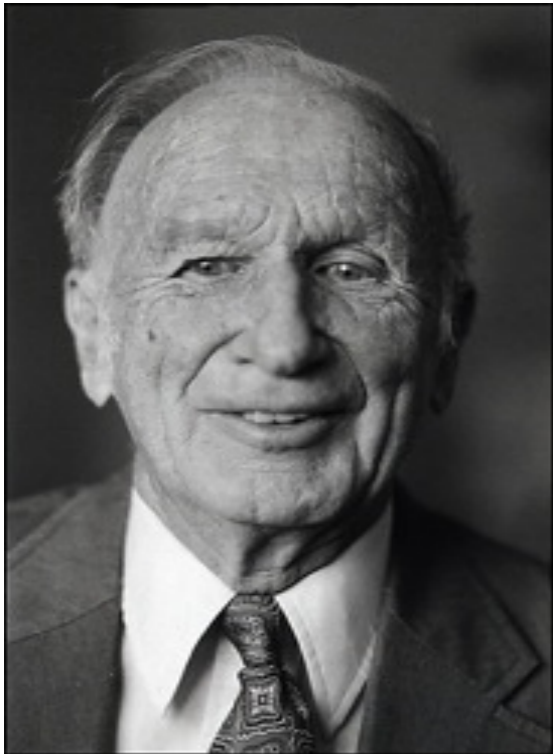
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The Butterfly Effect



Lorenz model: x-z projection of the evolution **100,000 points** initially uniformly distributed ($\sigma=.027$) in the neighborhood of $(6.27, 13.9, 19.5)$ that quickly spreads over the strange attractor.

Lessons from complexity in time?

– Multiplicative Ergodic Theorem (M.E.T.)

Lyapunov, 1907; Oseledets, 1968

$$|\delta \underline{X}(t)| \approx e^{\mu t} |\delta \underline{X}(0)|$$

– with the (finite) Lyapunov exponent:

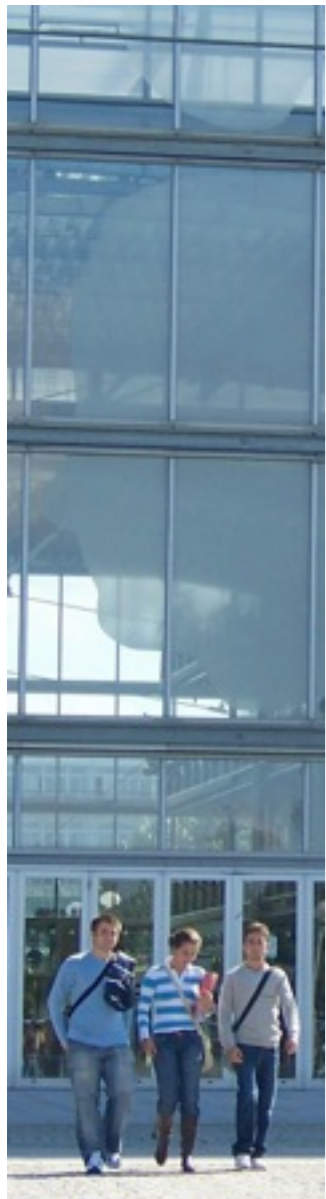
$$\mu = \langle \text{Log}^+ (\|D_X F\|) \rangle$$

Hints: pair separation is multiplicatively modulated by the derivative

+ existence of an ergodic measure that defines $\langle . \rangle$ averages



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Lyapunov exponent of Lorenz model

$$\mu(t) = \int_0^t dt \operatorname{Log}^+ \left(\left\| D_{X_t} F \right\| \right)$$

$$\bar{\mu} \approx 2.33341$$



Lessons from complexity in time?

- Liouville equation (**LE**) for intermediate times

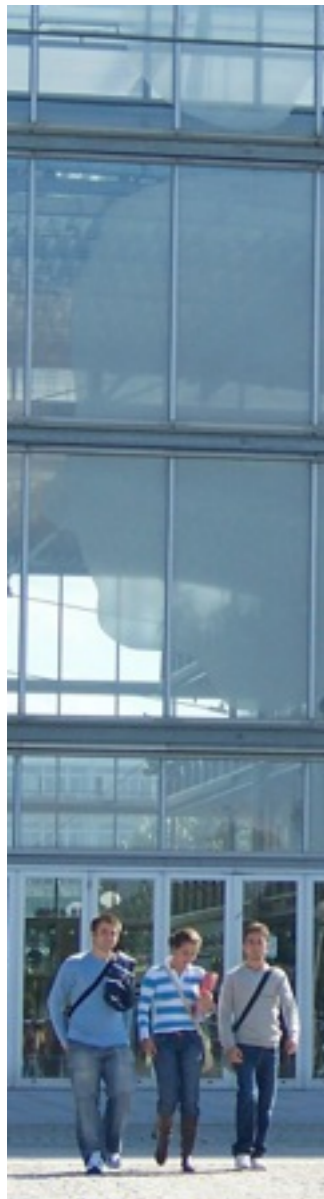
(Liouville, 1938) for any well-posed finite d -dimensional differential system, an ergodic measure exists and is regular w.r.t. the Lebesgue measure $dX_1 dX_2 \dots dX_d$

$$\frac{\partial}{\partial t} \rho(\underline{X}, t) + \sum_{i=1}^d \frac{\partial}{\partial X_i} \left[\dot{X}_i(t) \rho(\underline{X}, t) \right] = 0$$

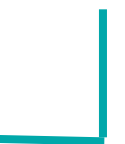
- i.e. a continuity equation of the density of the ergodic measure in the phase space



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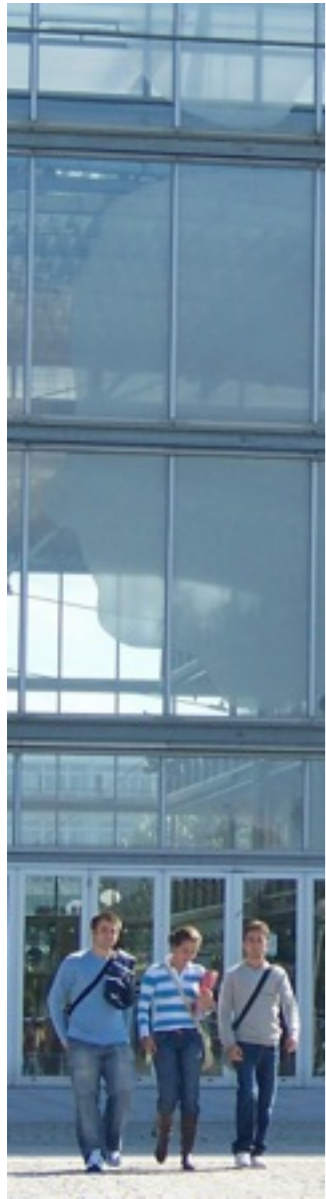
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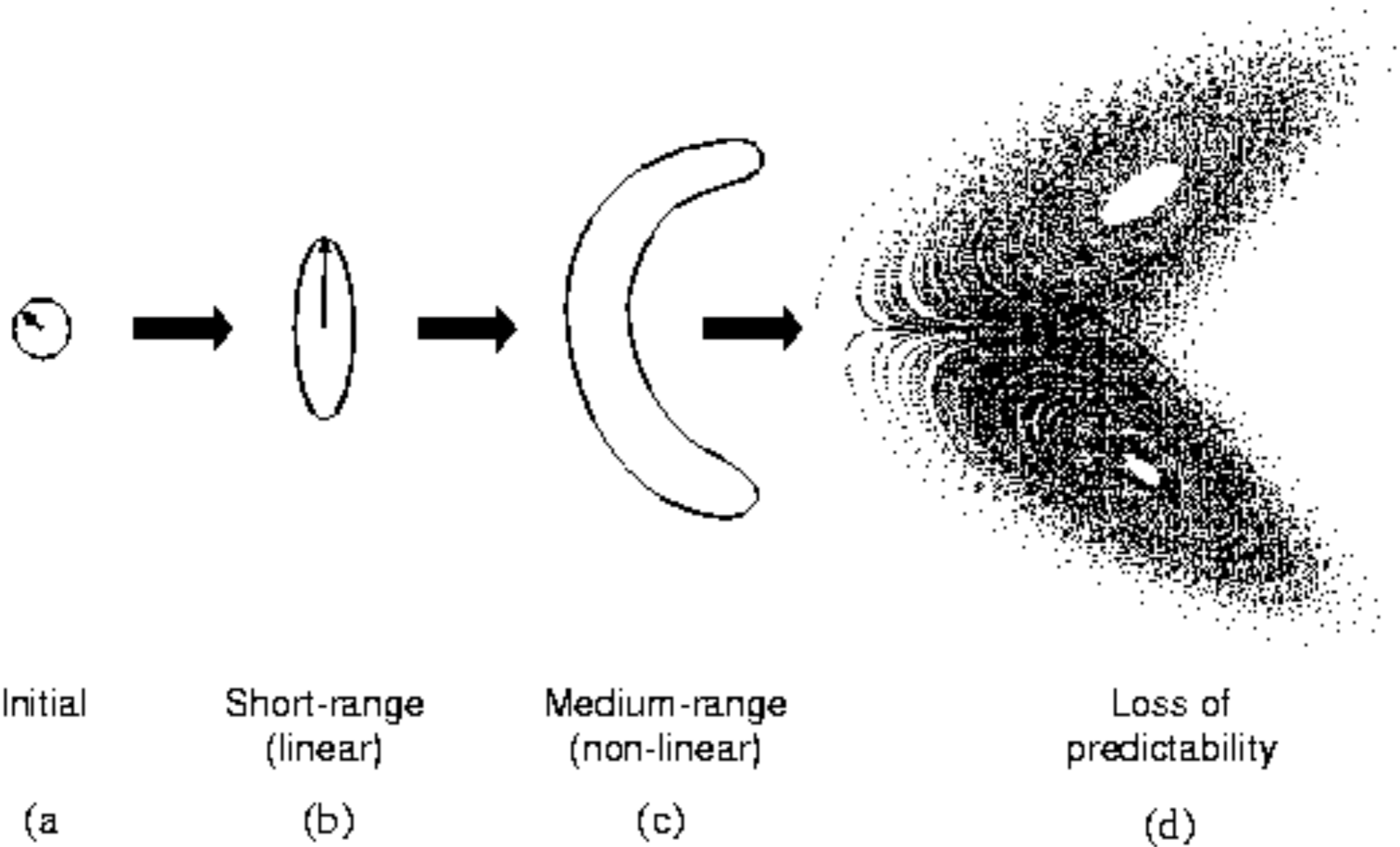
Butterfly effect and EPS



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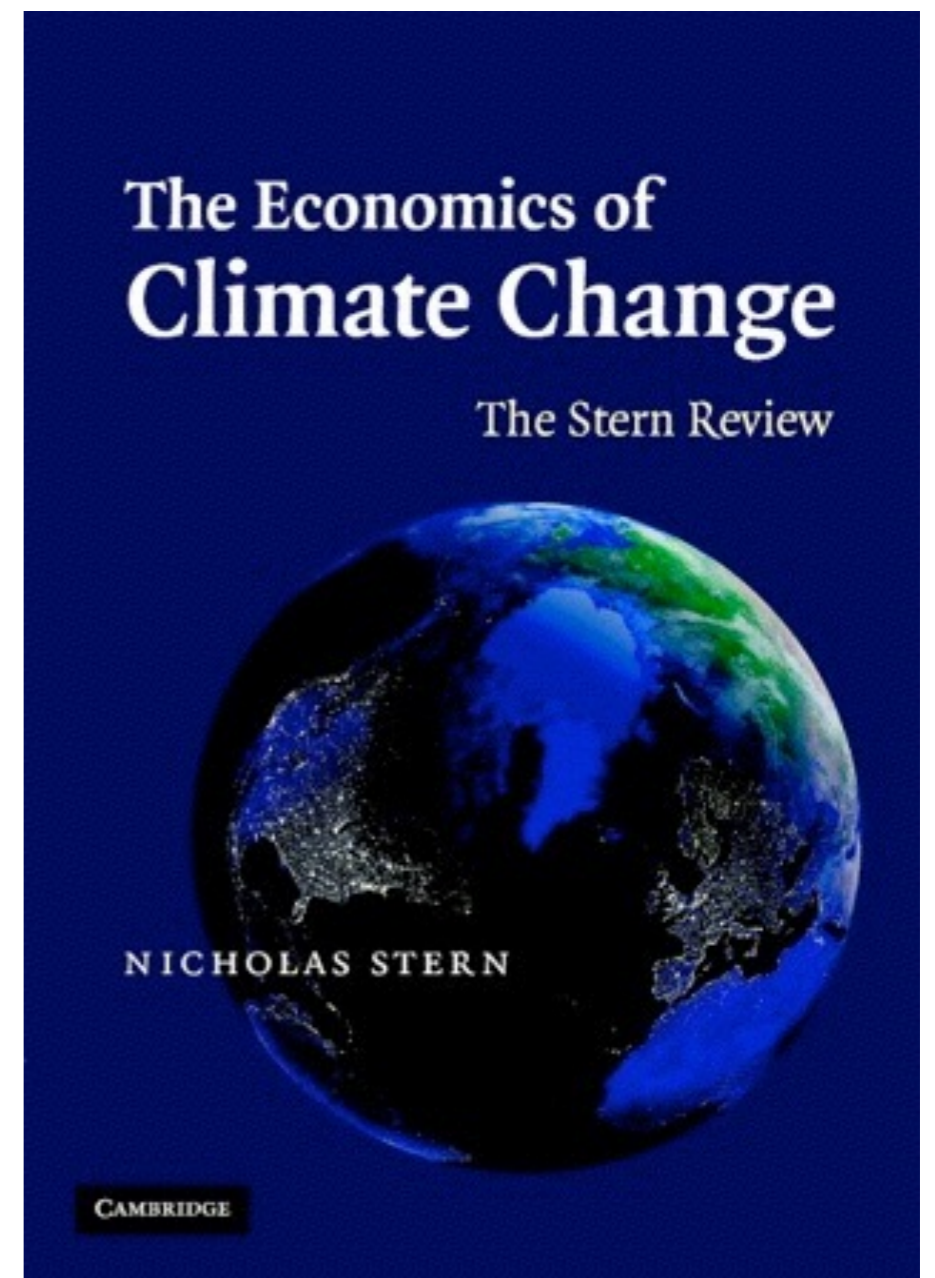
Scheme of the evolution of the empirical pdf evolution of an Ensemble Prediction System (EPS), according to Palmer, 1999: from the phase space region occupied by the initial ensemble (a), to (b) linear growth phase, to (c) nonlinear growth phase, to (d) loss of predictability (Palmer, 1993)

A million dollar problem with trillion-dollar implications!

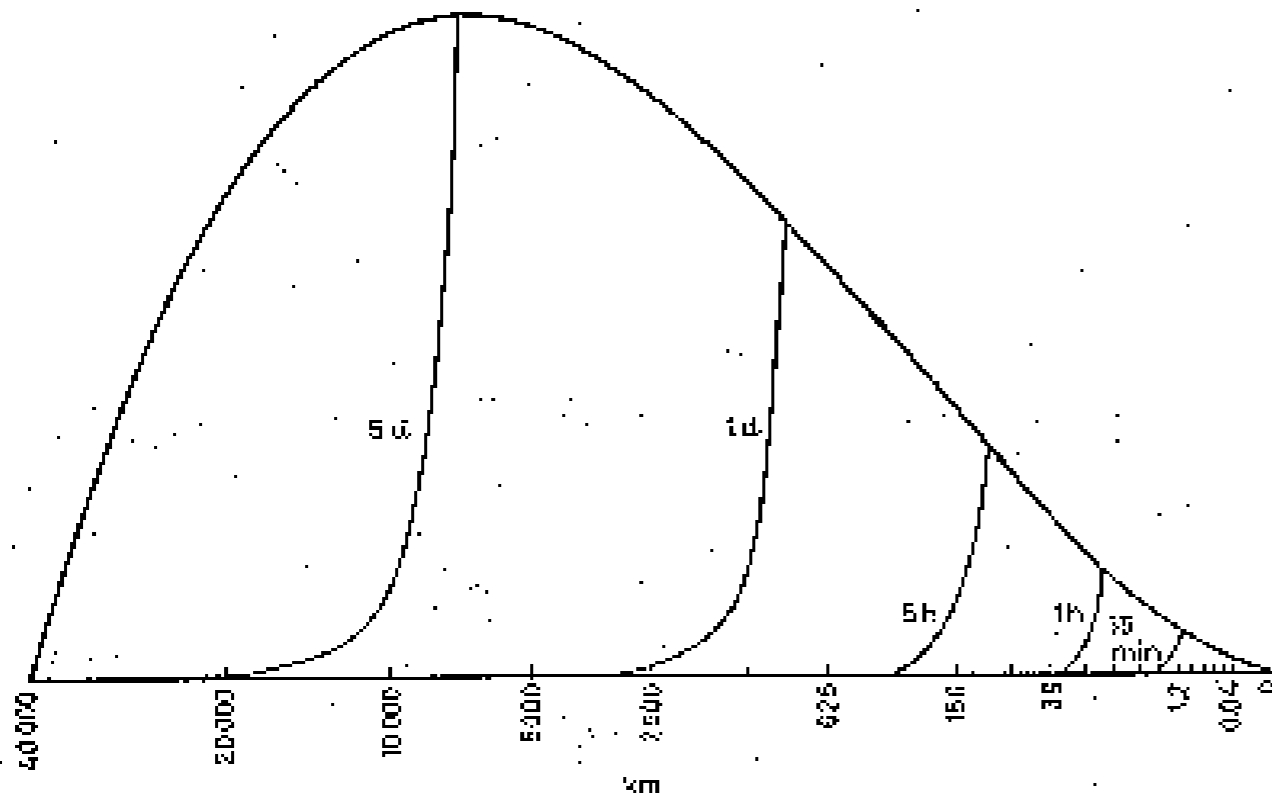
Is the butterfly effect really true?



Board of Directors and Scientific Advisory Board
Landon T. Clay, Lavinia D. Clay, Finn M.W. Caspersen,
Alain Connes, Edward Witten, Andrew Wiles, Arthur Jaffe
(not present: Randolph R. Hearst III and David R. Stone)



Spectral analysis and closures



Flux from correlated e^c
to
decorrelated energy e^Δ

Similar results with turbulence phenomenology:

$$\ell_c = 1/k_c \approx t^{3/2}$$

Lorenz (1969)

Leith and Kraichnan (1972),

Metais and Lesieur (1986)

$$e^c(\underline{x}, t) = \underline{u}^2(\underline{x}, t) \underline{u}^1(\underline{x}, t)$$

$$e^\Delta(\underline{x}, t) = \frac{1}{2} \left(\underline{u}^2(\underline{x}, t) - \underline{u}^1(\underline{x}, t) \right)^2$$

$$\ell_c^{2/3} = \bar{\varepsilon}^{-1/3} t^{3/2}; \quad \bar{\varepsilon} = 10^{-3} \text{ m}^2 \text{ s}^{-3}, \quad \eta \approx 10^{-3} \text{ m};$$

Turbulence phenomenology

The **eddy turn-over time** is the characteristic time, if it exists, for structures of scale ℓ

to "turn over" within a velocity shear $\delta u(\ell)$: $t \approx \ell / \delta u(\ell)$

It is also proportional to their time-life (Robinson, 1971) therefore the rate of energy transfer to smaller scales is:

$$\varepsilon(\ell) \approx \delta u^2(\ell) / \tau(\ell) \approx \delta u^3(\ell) / \ell$$

Assuming scale invariance of the energy flux (K41):

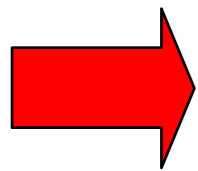
$$\varepsilon(\ell) \approx \bar{\varepsilon}$$

$$\mu(\ell) \propto 1/\bar{\tau}(\ell) \propto \bar{\varepsilon}^{-1/3} \ell^{-2/3}$$

Small scale divergence !

$$\ell_e(t) \propto \bar{\varepsilon}^{-1/2} t^{3/2}$$

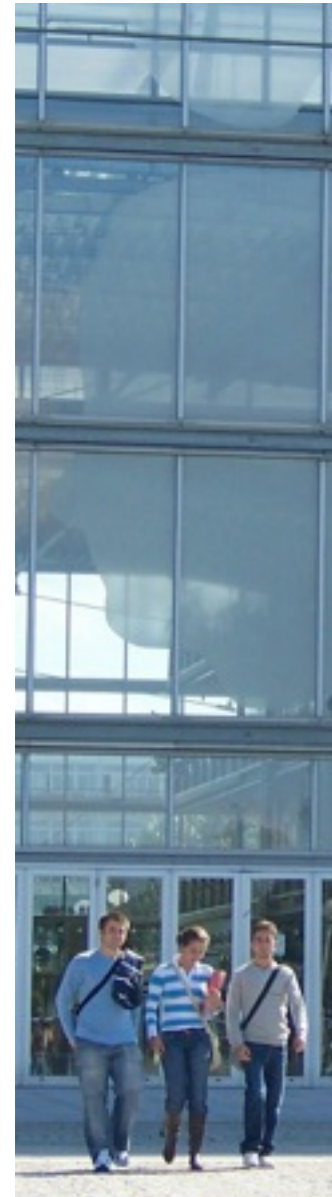
uncertainties grow up to larger scales according to a power-law!



How to generalize turbulent phenomenology?



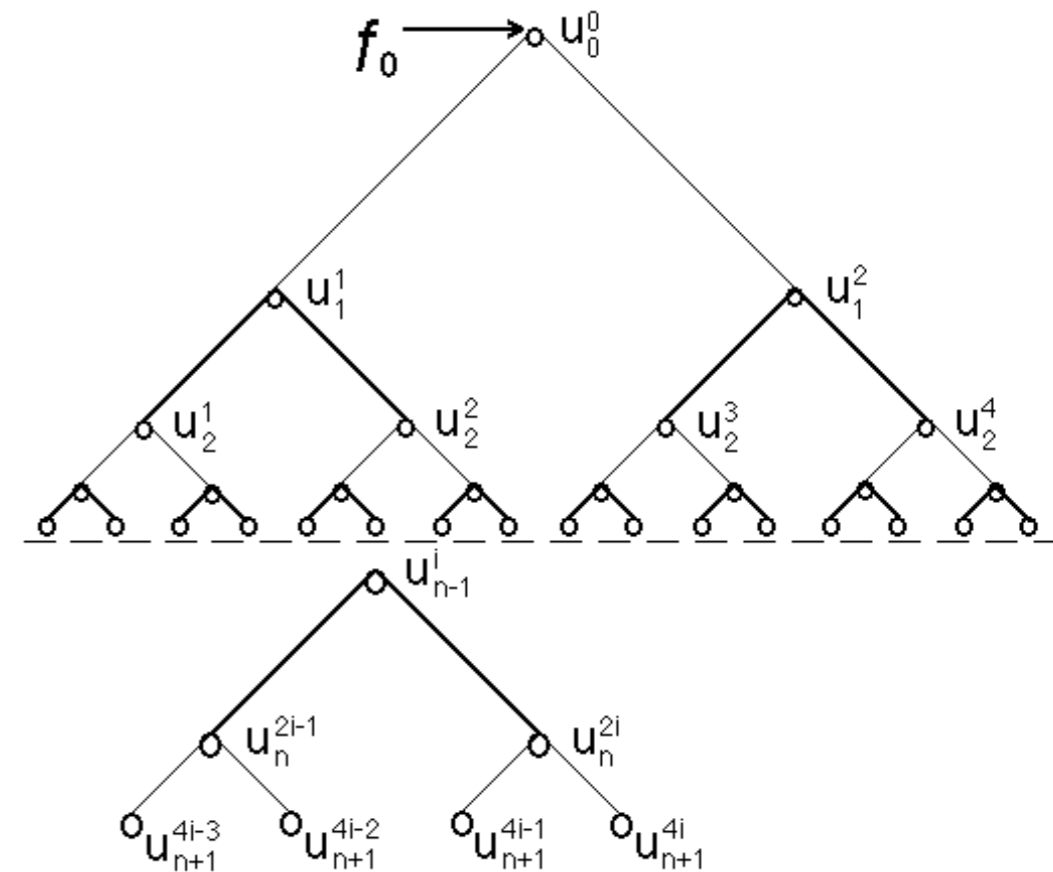
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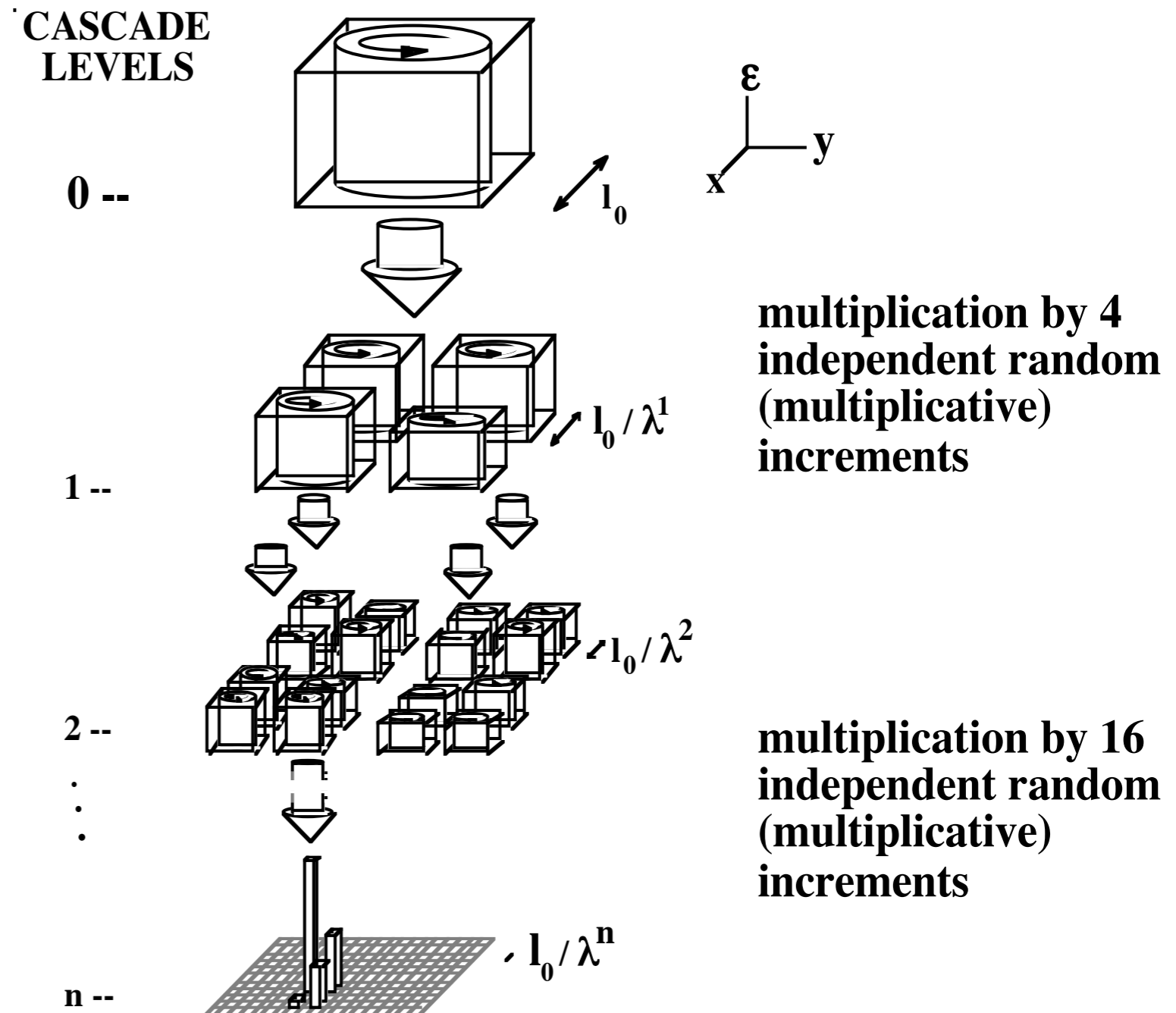
- How to include:
 - intermittency, :
 - strongly non gaussian statistics,
 - scaling anisotropies:
 - Time vs. space:
 - Vertical vs. horizontal:
 - atmosphere is neither 3D, nor 2D, but rather $23/9D$?
- Use (anisotropic) time-space cascades :
 - Outcome: multifractals in the framework of GSI

Hierarchy of space-time structures



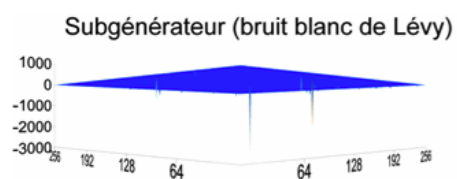
Pedagogy: multiplicative cascades

- Richardson poem:
Big whorls have little whorls...
- discrete multiplicative cascade processes (Yaglom 1966, Mandelbrot 1974...)
- from dead/alive alternative (β -model)
- to weak/strong infinite hierarchy of intensities
- supported by an infinite hierarchy of fractals,
- i.e. these fields are in general **MULTIFRACTAL**
- DISCRETE CASCADES are mostly for PEDAGOGY !
 - multiplicative processes are not indispensable !
 - no causality !

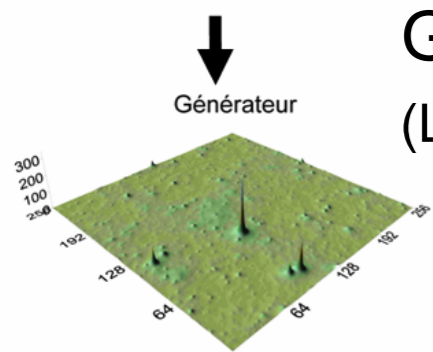


From discrete to continuous and universal cascades

Hint: multiplicative process=exponential of an additive process, but with **a small scale singular limit !**



Sub-generator $\gamma_{0,\lambda}$ white-noise
(UM: Lévy-noise, index α , $\beta=-1$)

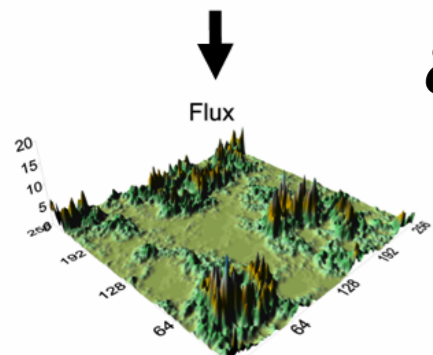


Generator Γ_λ :
(Log λ divergence)

$$-(-\Delta)^\beta (\Gamma_\lambda) = \gamma_\lambda, \quad \beta = D_{el} / 2\alpha',$$

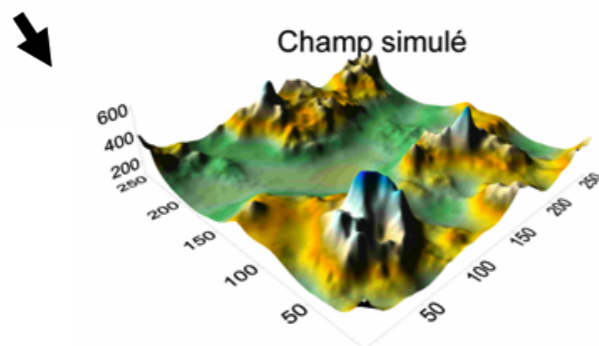
$$1/\alpha + 1/\alpha' = 1$$

$$d\varepsilon_\lambda = \varepsilon_\lambda d\gamma_\lambda$$



ε_λ

$$d\gamma_\lambda - d\Gamma_\lambda = \frac{\text{var}(\alpha)d\lambda}{\lambda}; \quad \text{var}(\alpha) = \frac{C_1}{\alpha - 1}$$



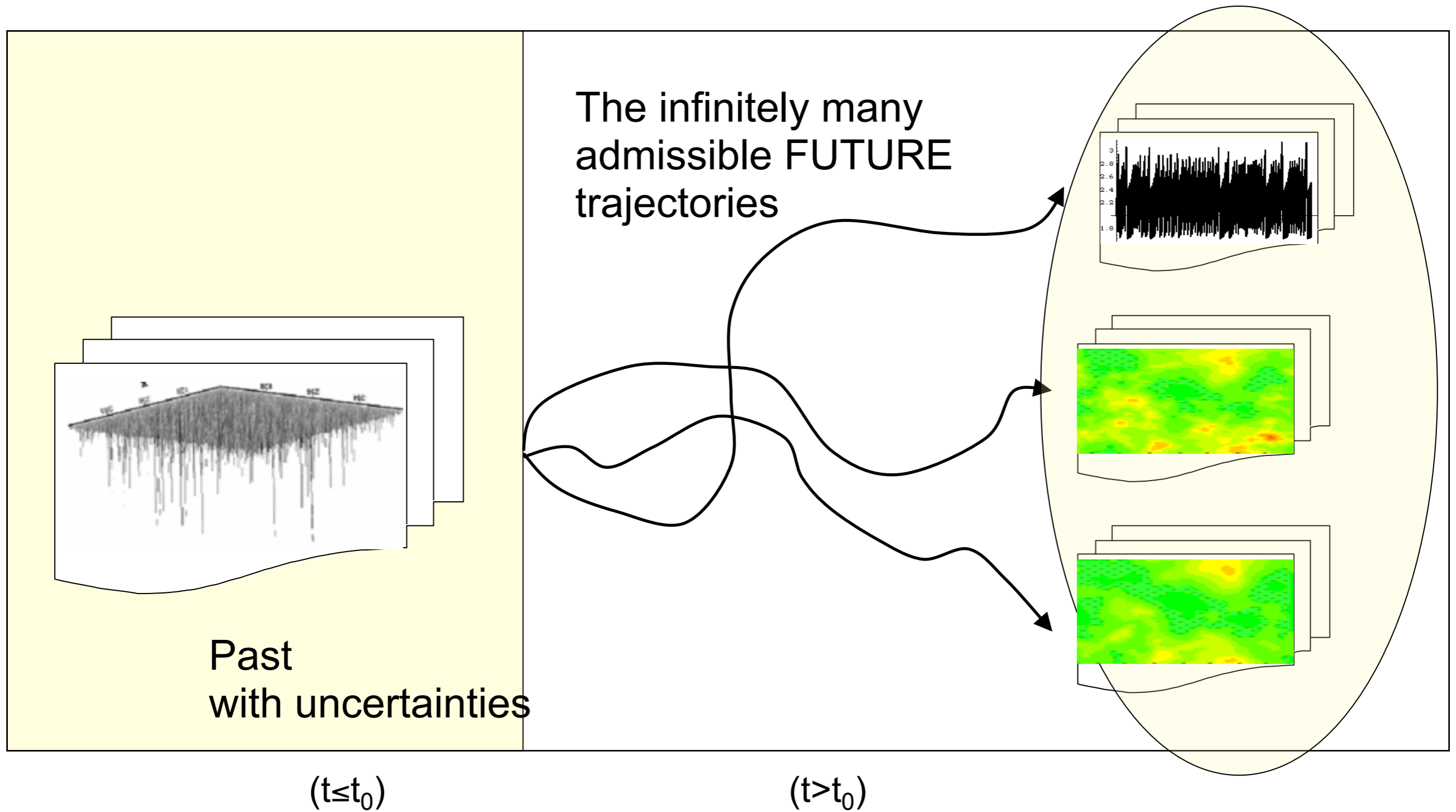
Field ρ_λ

$$-(-\Delta)^{\beta'} (\rho_\lambda) = \varepsilon_\lambda$$

$$\beta' = (D_{el} - H) / 2$$

U.M.= stable fixed points
of a multiplicative CLT

Forecasts and past memory



Multifractal Predictability



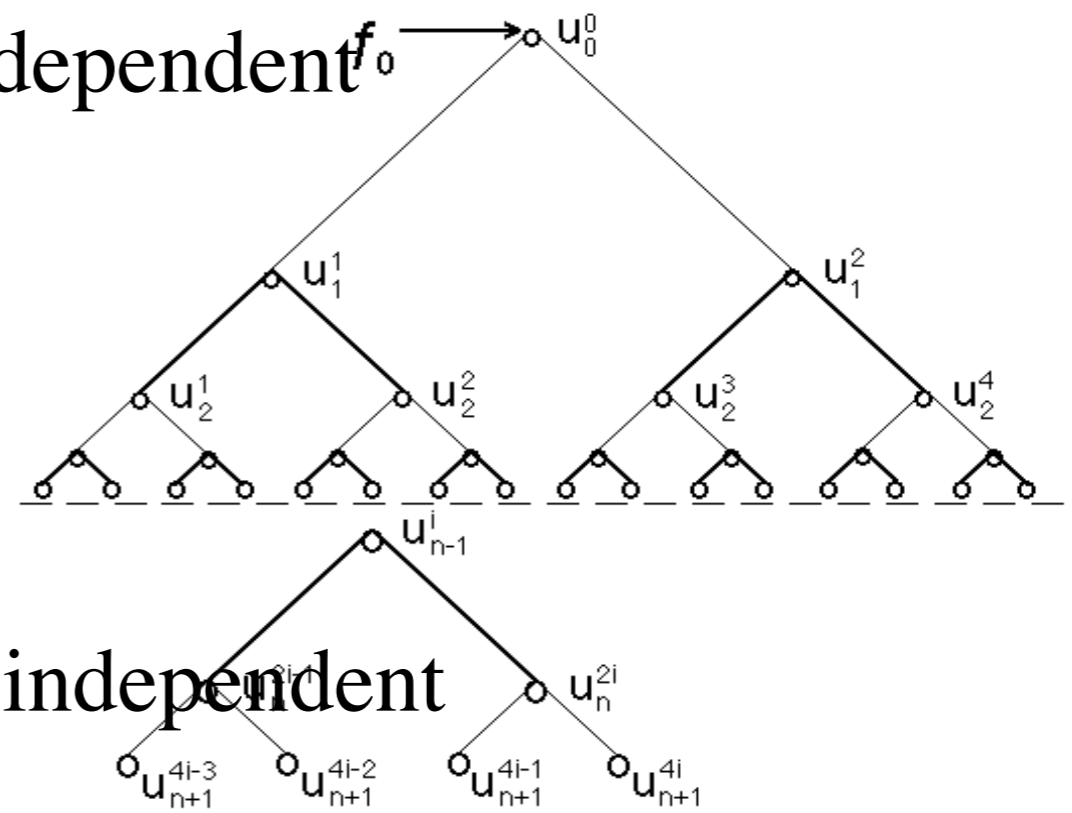
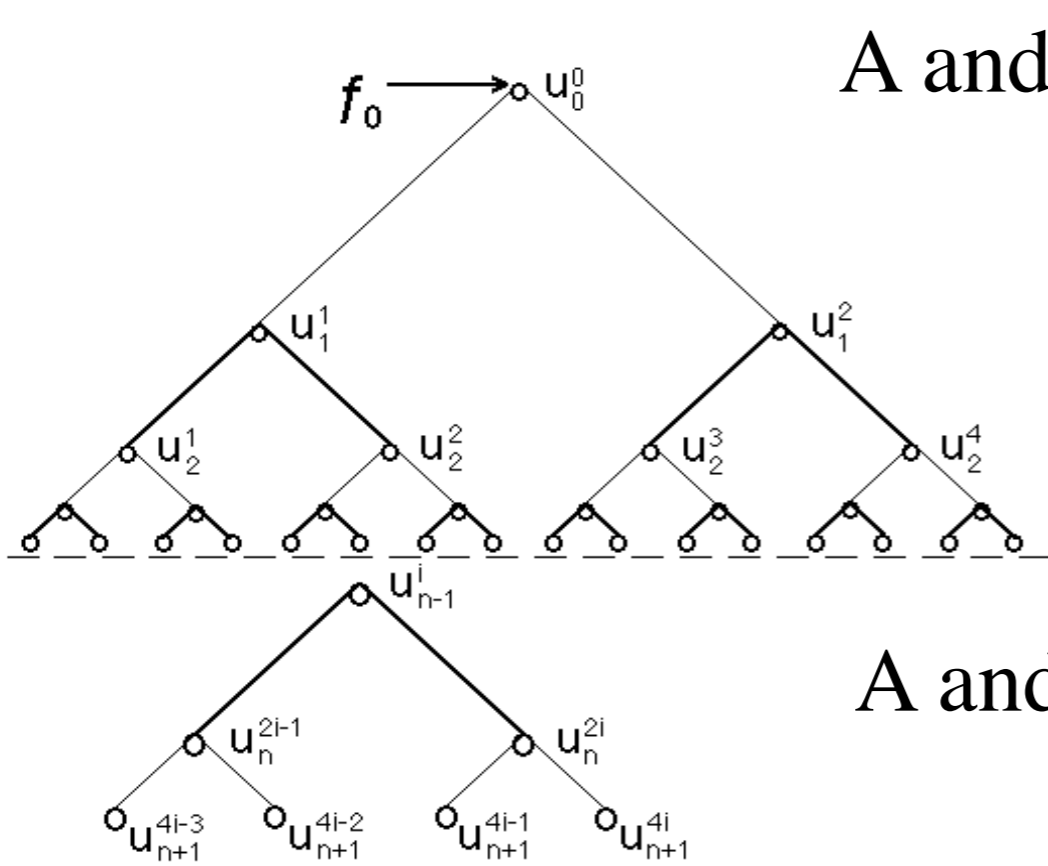
Crude idea:

relaxation of (common) past structures \implies flux of the past

(new) independent structures \implies flux of the future

Cascade A

Cascade B



A and B strongly dependent

A and B strongly independent

L

$L/\lambda(t)$

L/Λ

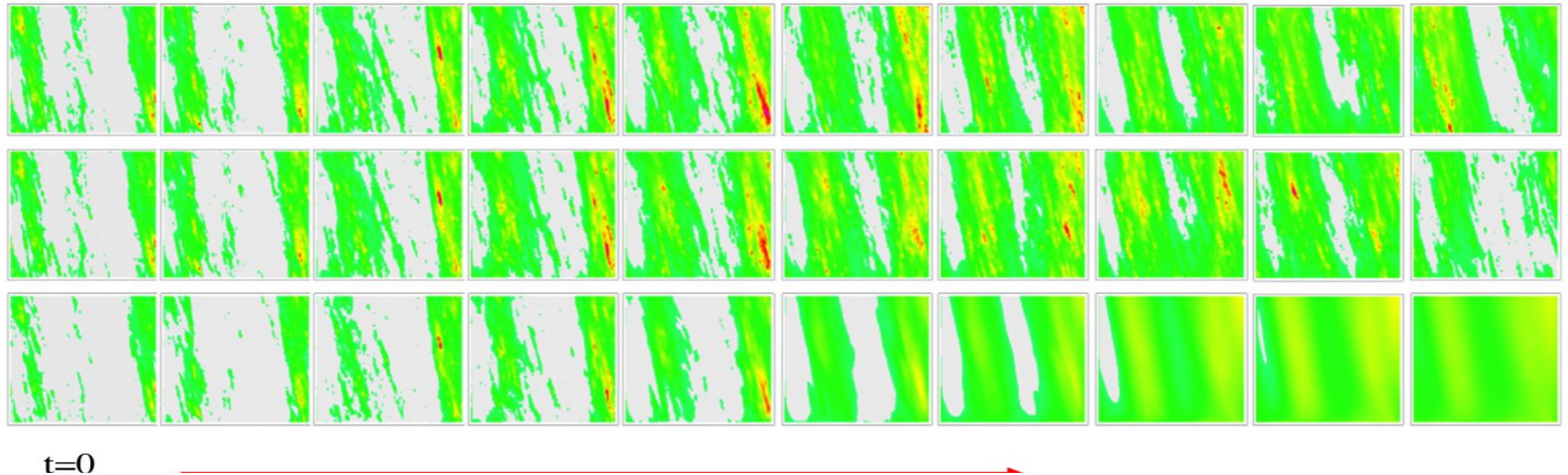


Multifractal predictability



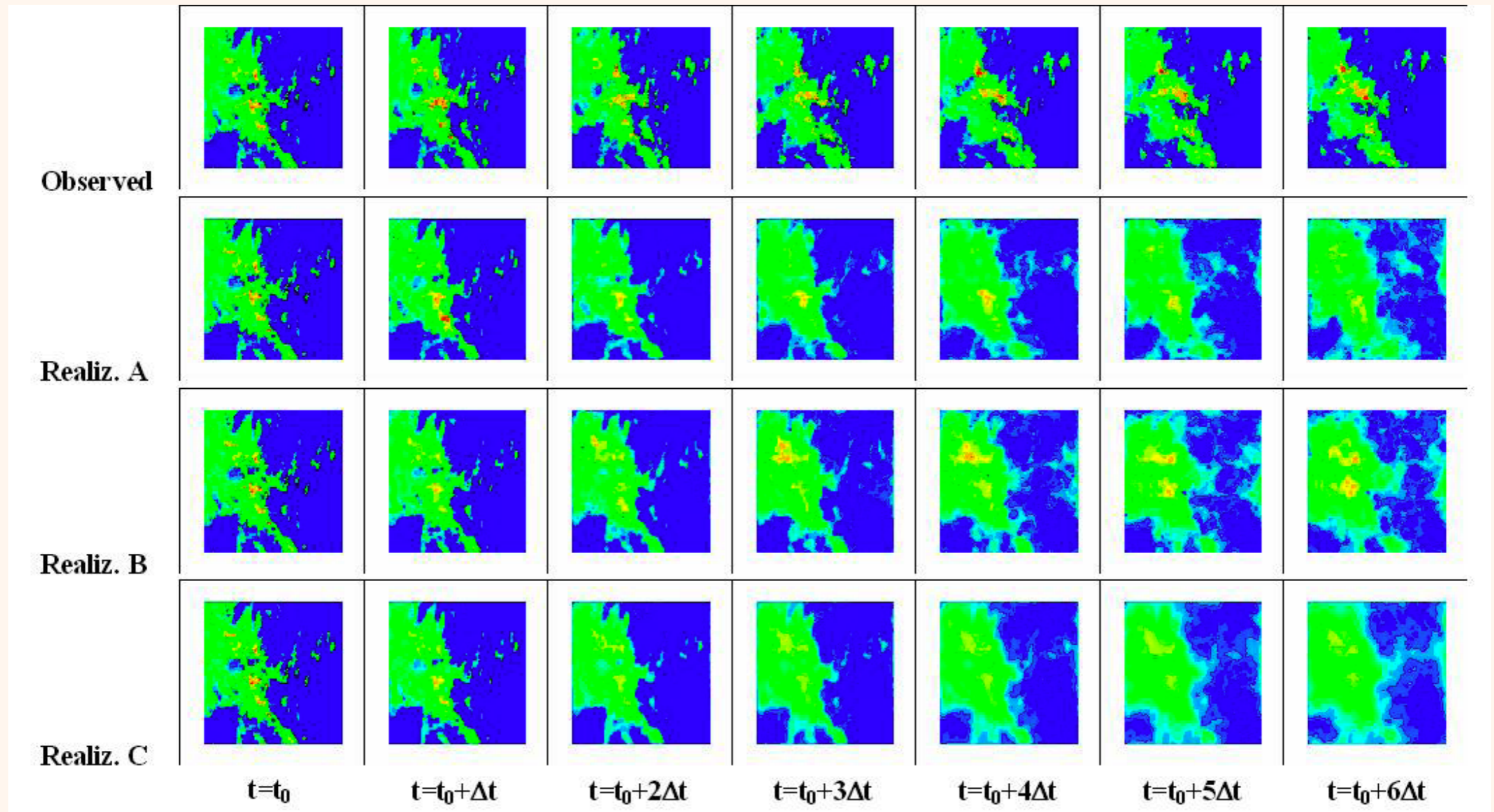
Rain simulation ($\alpha=1.5$, $C_1=0.2$, $H=0.1$ on log scale. Realizations A, B are identical until $t=0$, then they diverge.

Top: Realization A. Middle: Realization B. Bottom, forecast

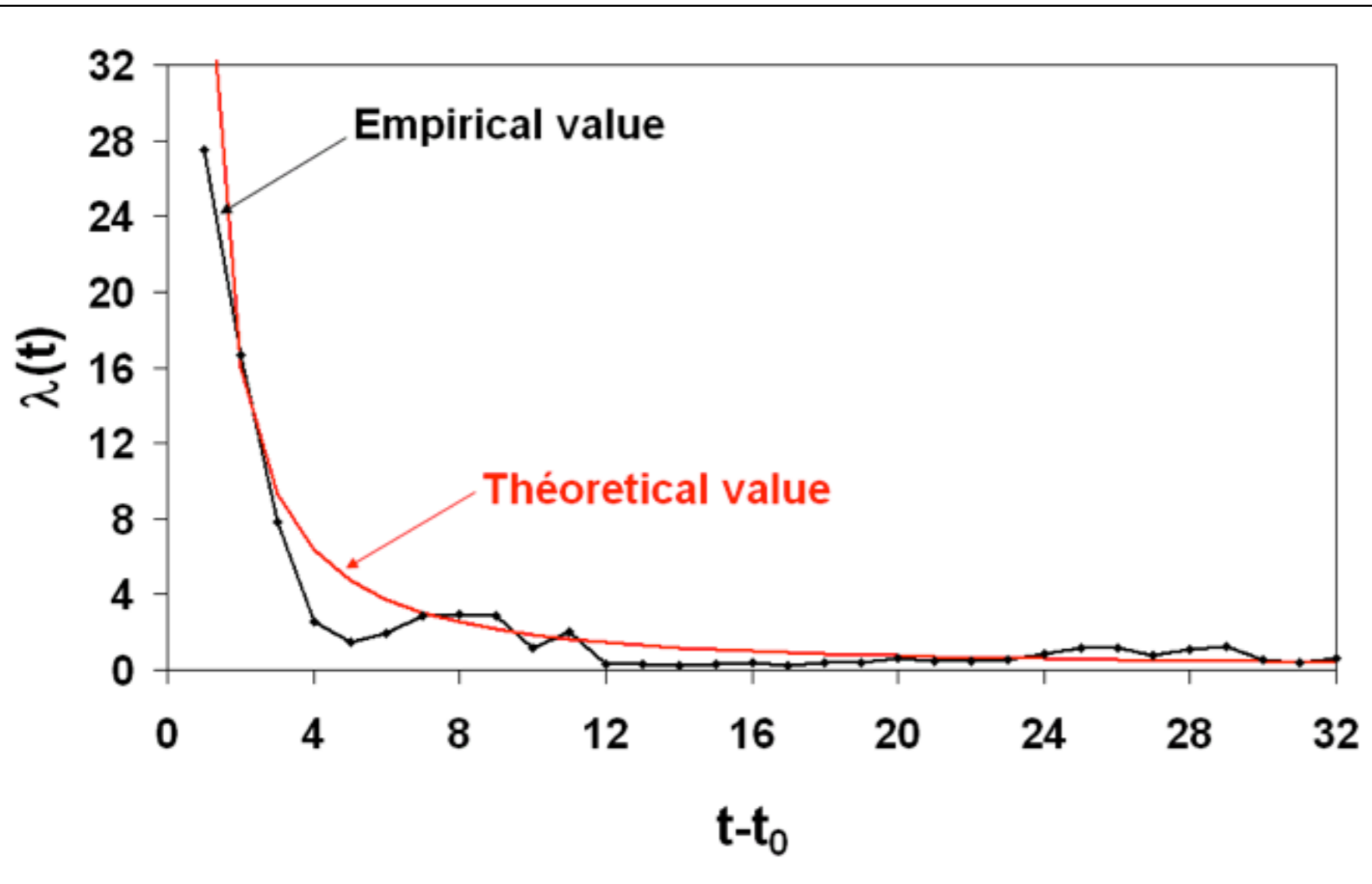


- **Power law divergence** between the realizations A and B,
 \Rightarrow **irrelevance** of the finite dimensional ‘LE + MET’ scenario !
- **Drastic loss of variability of forecast C** with deterministic sub-grid modeling (based on the conservation of the flux) \Rightarrow ‘**baby theorem**’: **stochastic sub-grid modeling** does much better than deterministic one!

Forecasts based on radar data

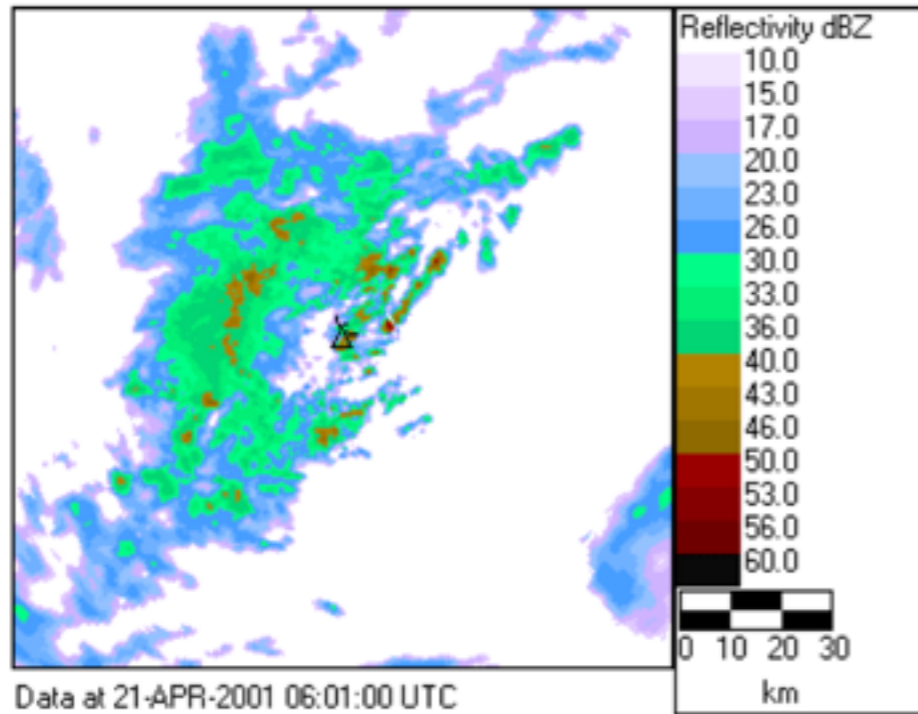


Power law decay of the common scale ratio



Power law decay
of the scale ratio
 $\lambda(t)$ on which A and
B are strongly
dependent

STEPS



STEP is a BOM operational product based on a simplification of multifractal forecasts

Figure 8 Field of radar reflectivity. The field is from Melbourne, Australia, and is a 256 x 256 km image with 1 km resolution.

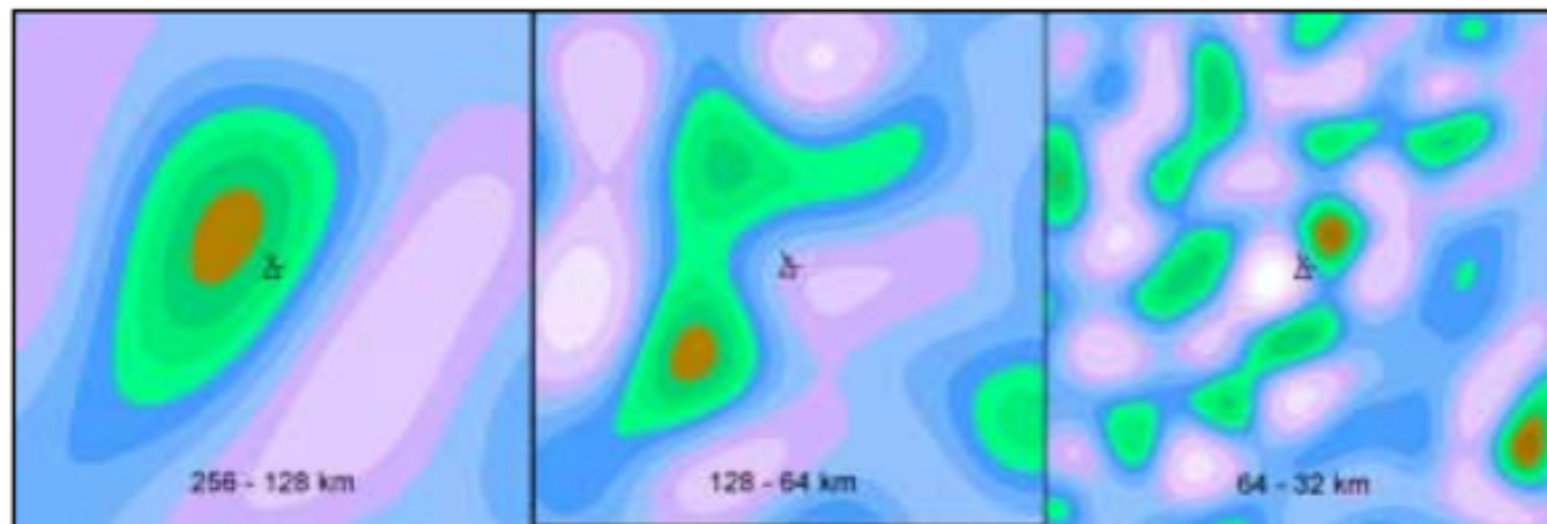


Figure 9 The first three spectral components of the field in Figure 8

(Seed, 2009)

STEPS

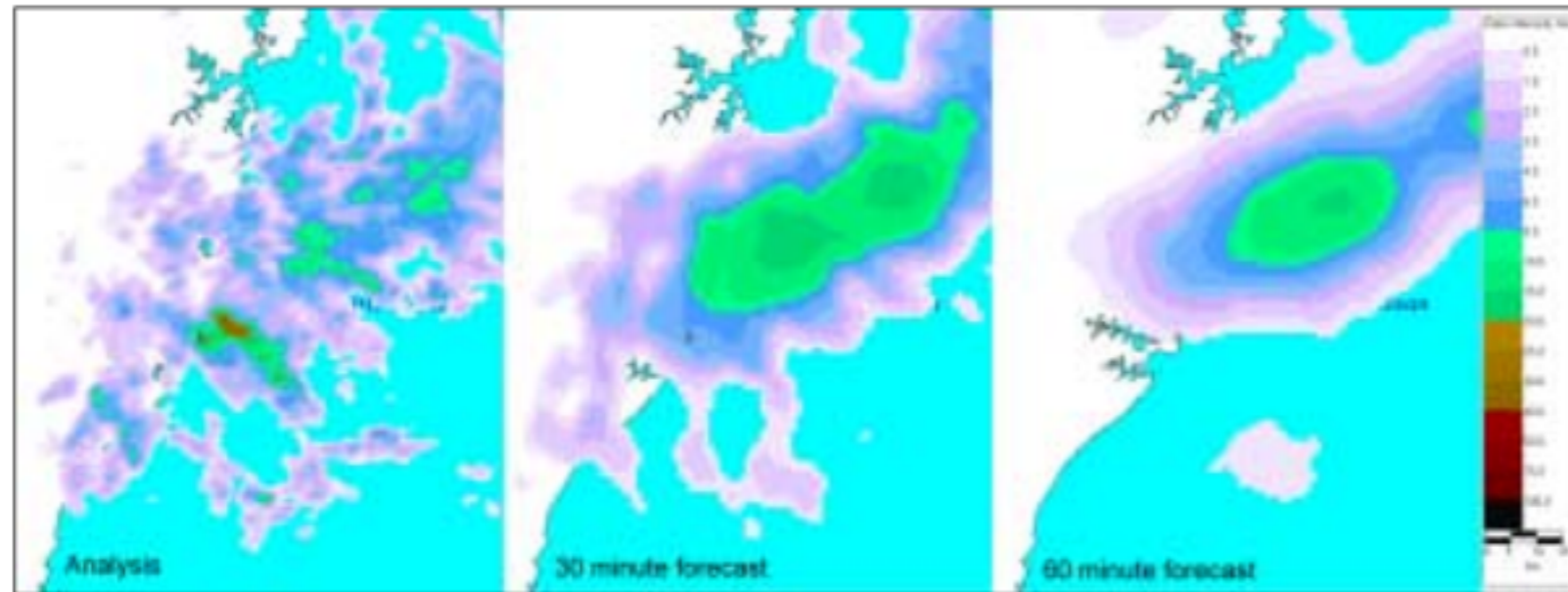


Figure 10 Analysed rainfall, 30- and 60-minute deterministic forecasts of rainfall for the Sydney area for 12:15 12 May 2003

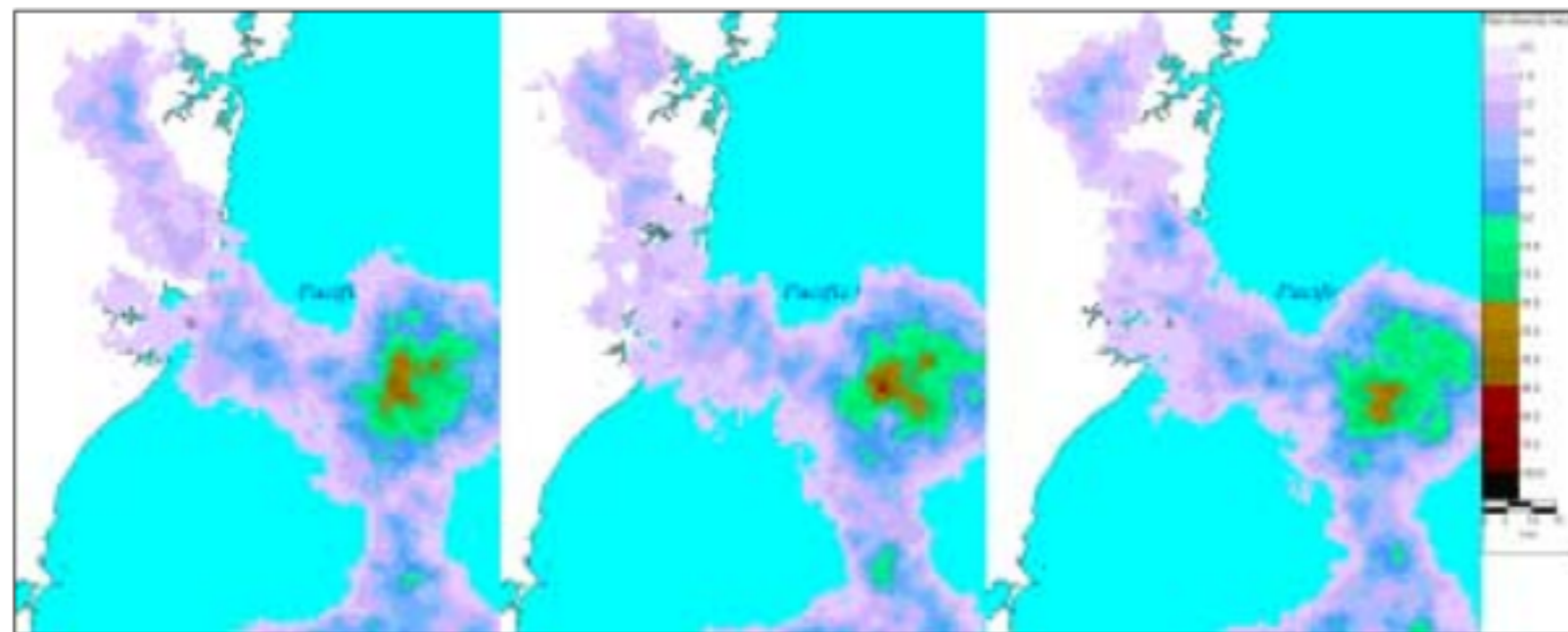
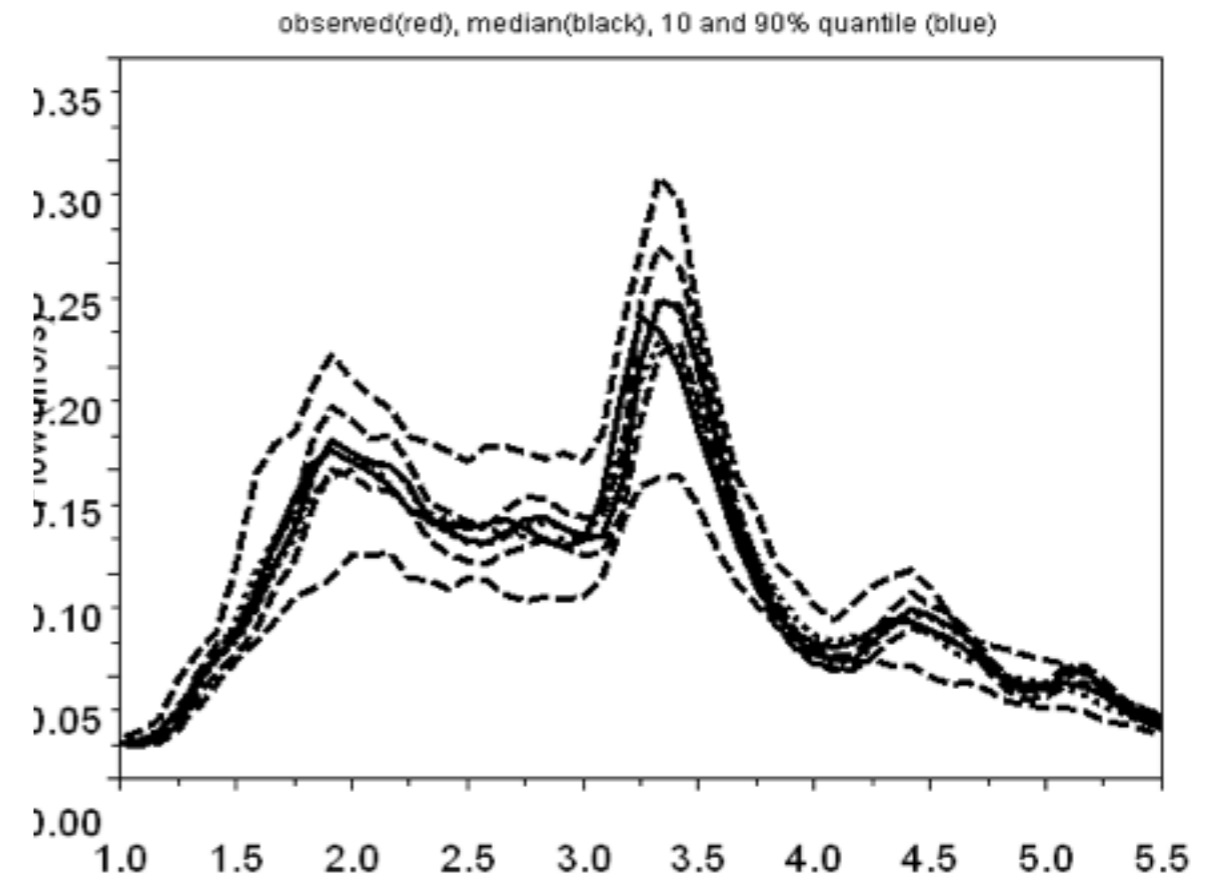
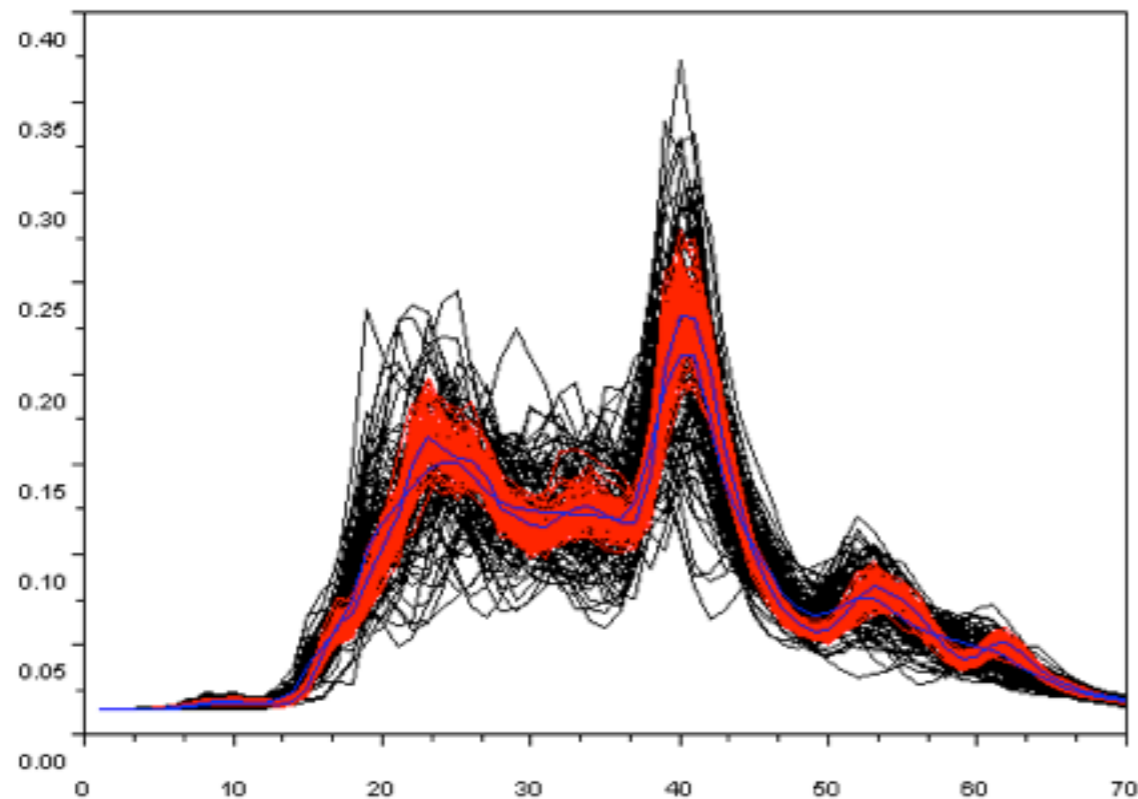


Figure 11 An ensemble of three 1-hour stochastic nowcasts of rainfall over Sydney.

Small scale variability

Stochastic ensemble (1000 realisations) of multifractal downscaling



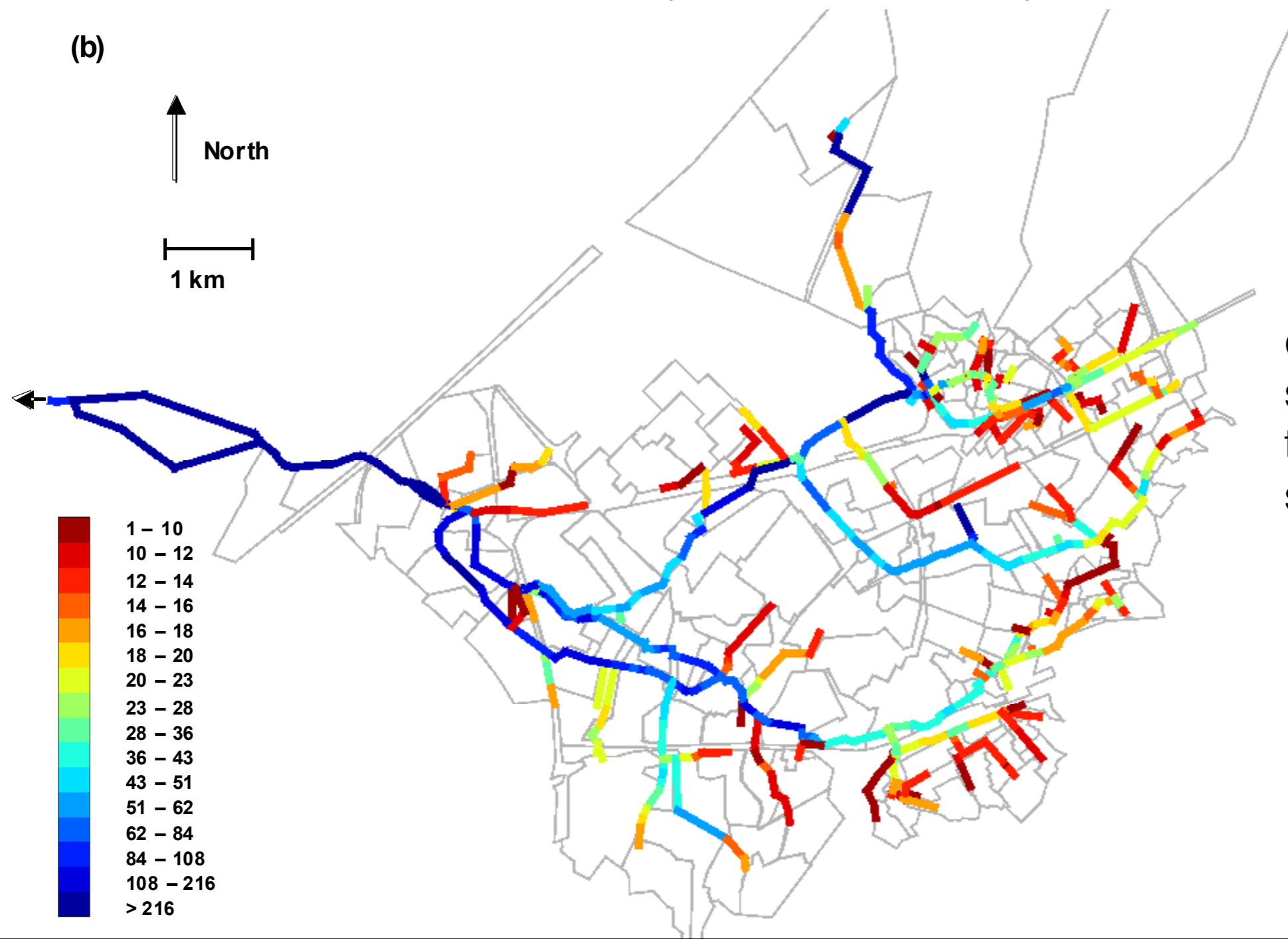
- 1000 downscaling realisations: 1km -> 125 m
- 1000 downscaling realisations: 8 km -> 125 m
- Q_{radar} (1 km)
- $Q_{0.9}$ et $Q_{0.1}$ (125 m)

(Gires, eta l., 2010)

Small scale variability



Stochastic ensemble (1000 realisations) of multifractal downscaling



Estimates of peakflow quantile increases due to small scale variability of the rainfall of in a sewer system in Paris region

Gires, et al., 2011)

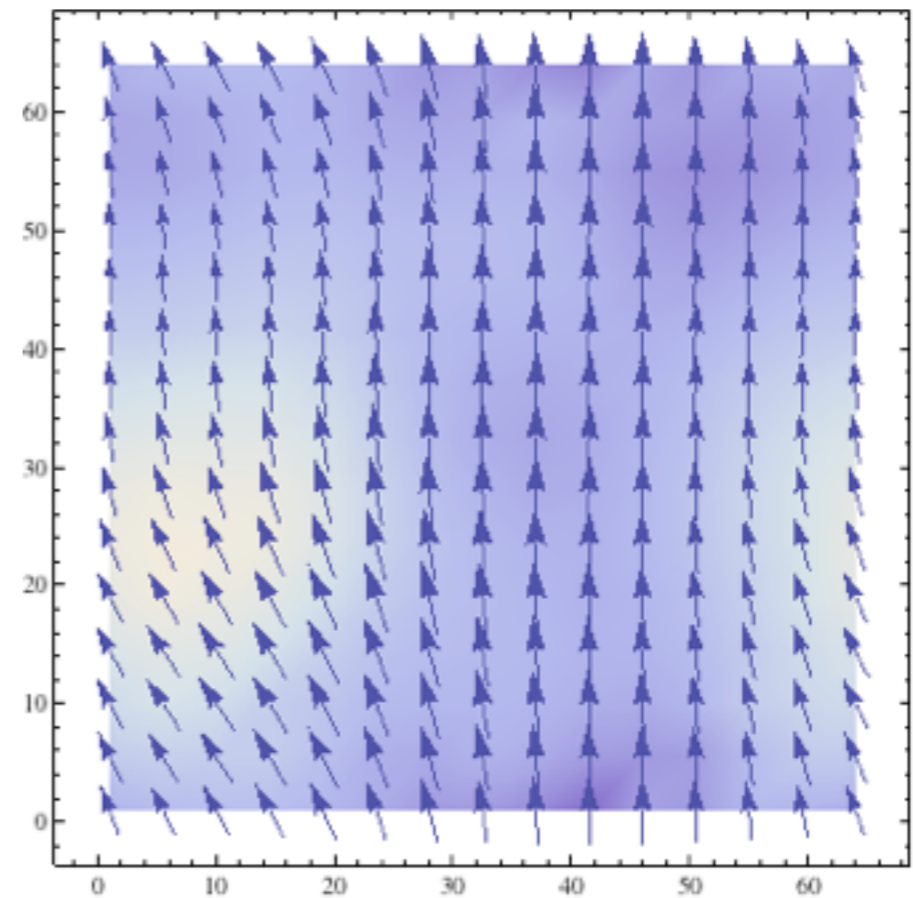
Surface layer complexity!

explOatorium®

WAUDIT Wind resource assessment
audit and standardization



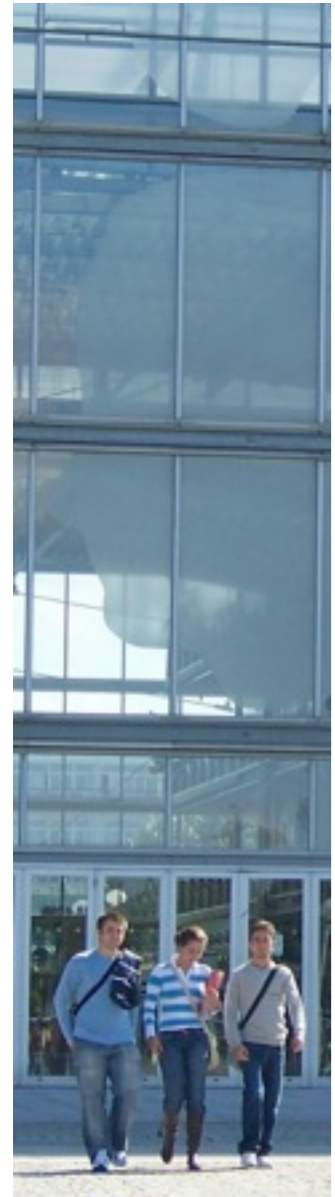
Art piece 'Windswept' (Ch. Sowers, 2012): 612 freely rotating wind direction indicators to help a large public to understand the complexity of environment near the Earth surface



Multifractal FIF simulation (S et al., 2013) of a 2D+1 cut of wind and its vorticity (color). This stochastic model has only a few parameters that are physically meaningful.

Both movies illustrate the challenge of the near surface wind that plays a key role in the heterogeneity of the precipitations... and wind energy!

Conclusions



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- Multifractal/cascade processes
 - not only help to clarify the predictability of space-time complex systems,
 - but yield concrete methods to dynamically forecast within this predictability limit by:
 - exploiting the past memory
 - yielding admissible futures
 - already generated an operational product (STEPS)
- still interesting/complex problems, e.g.:
 - how to accurately estimate the past generator from real data (deconvolution)
 - therefore from ‘imperfect’ data
 - what about wind field (added value)?
 - Fokker-Planck equation for MF processes?
- Funding: UE Alban Program, UE FLOODSITE, CNRS/PNRH, RainGain

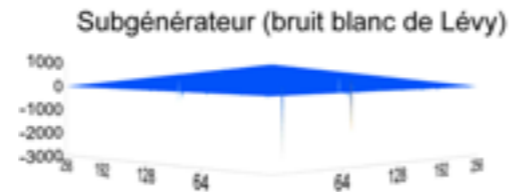


Forecasts and past memory

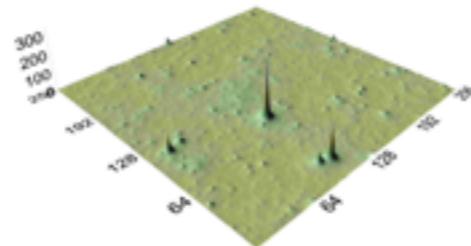
How to compute a possible FUTURE outcome



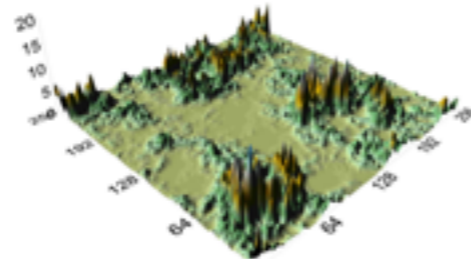
Illustration of a continuous cascade simulation from the subgenerator (white noise) to the field (fractionally Integrated Flux)



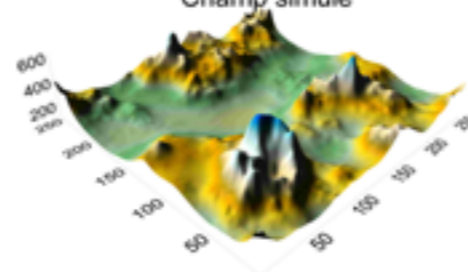
Générateur



Flux



Champ simulé



How to use the memory of the PAST

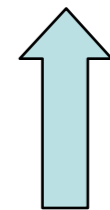


Illustration of the 'deconvolution' of past data to extract the past generator from the observed field

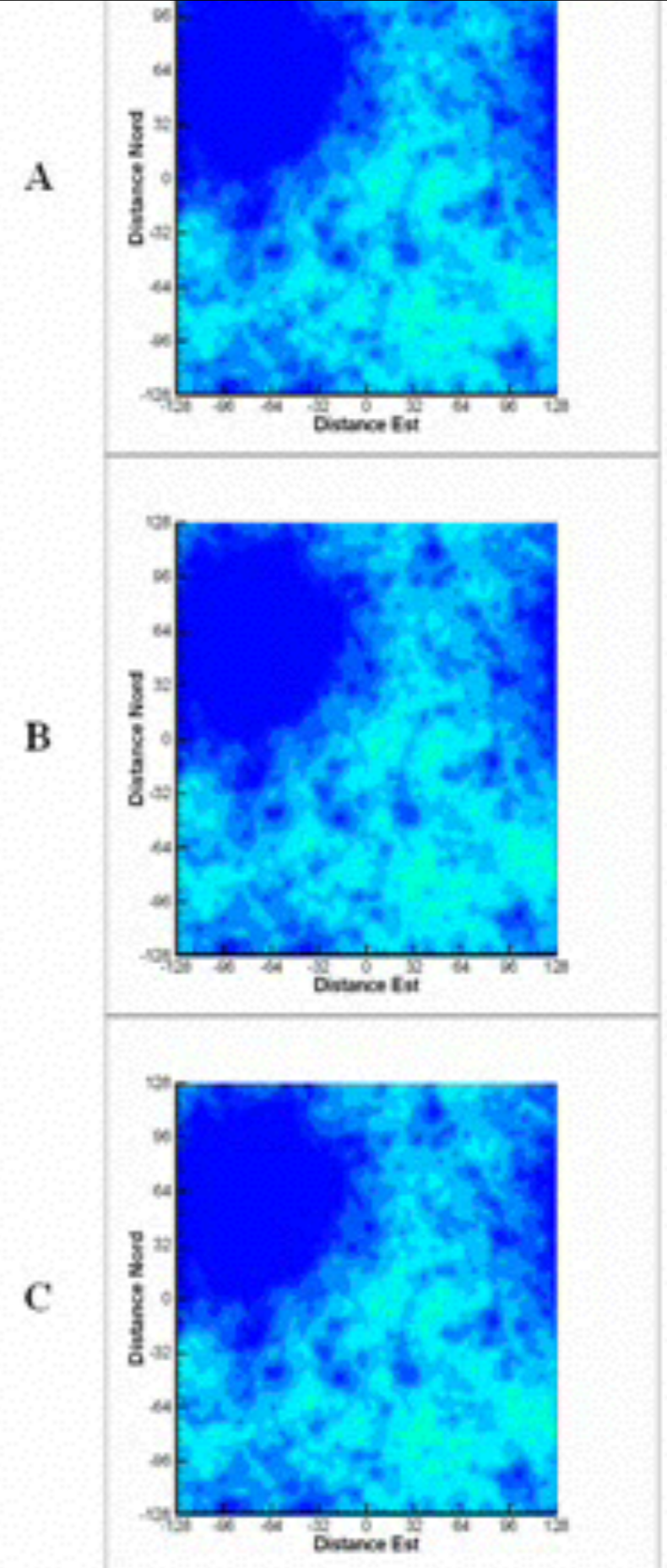
FORECAST: Combine the two generators to get the total flux and the total field

Examples of forecasts

Realisations A,B,C (252^2)
have common past
($t=0, t_0=32$) for $t= 0, 64$:

A B are 2 stochastic forecasts:
similar complexity

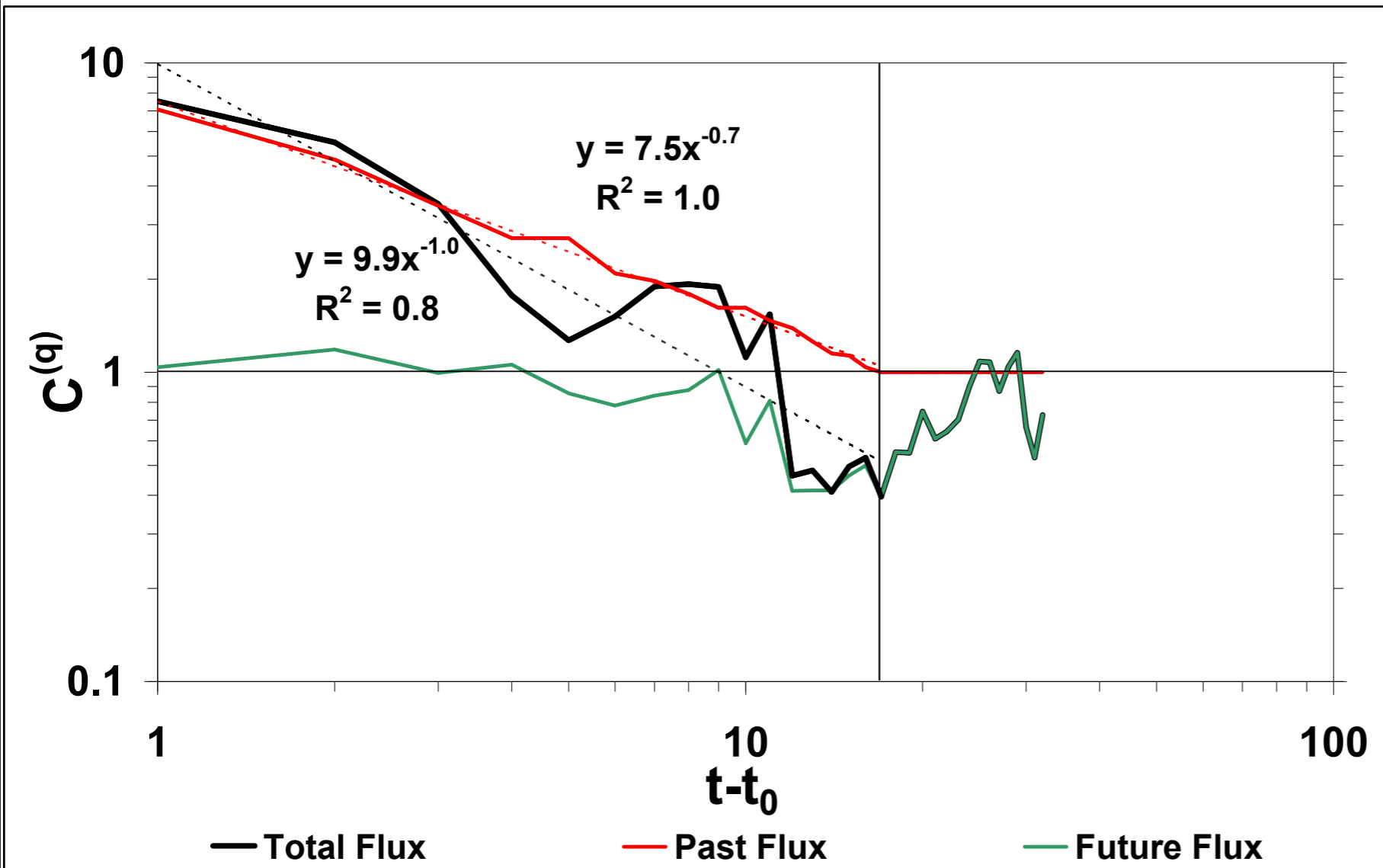
C is a deterministic forecast :
relaxation of the past structures,
the small scale complexity is
lost !



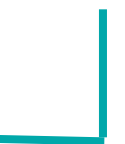
Decay of past information



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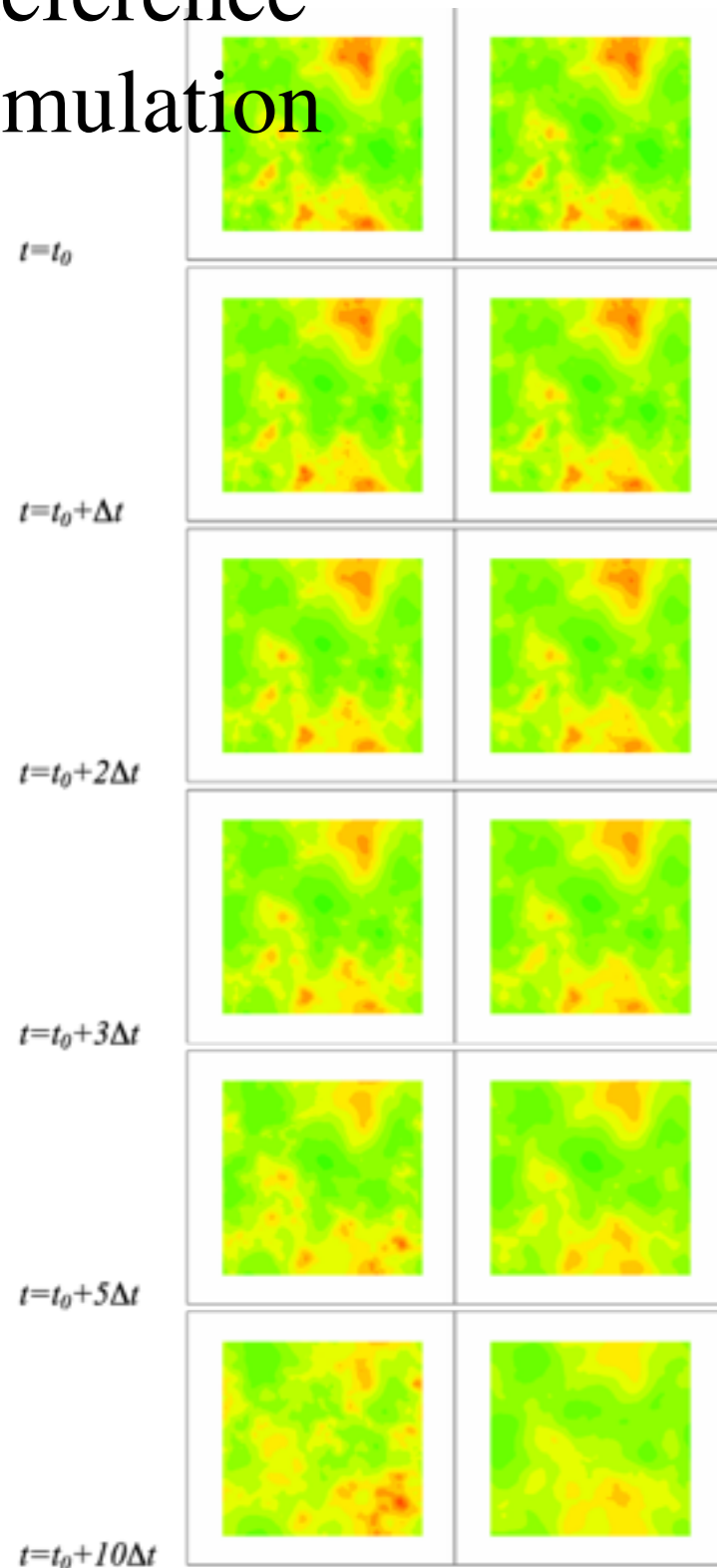


Correlation analysis of Fluxes:
-similar for the total flux and that of the past,
-future flux correlation
- only oscillate around unity (stochastic conservation).



(naive) ensemble prediction

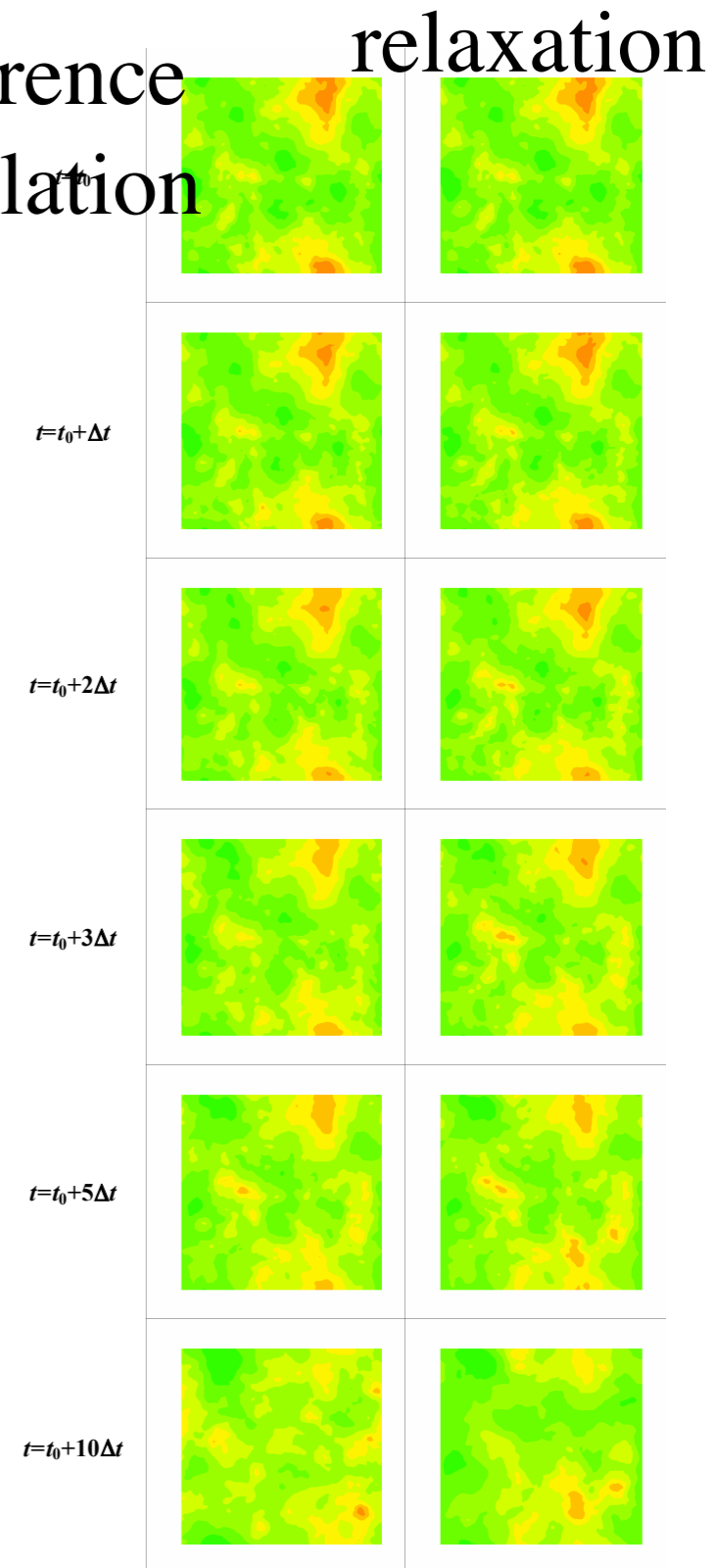
Reference
simulation



$$\alpha = 1.8, C_1 = 0.1,$$
$$H = 1/3, H_t = 1/3, \lambda = 256$$

Average of 20 forecasts
(independent flux
subgenerators):
still rather blurred...

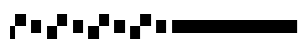
Reference
simulation




Fundamental problem: nonlinearity

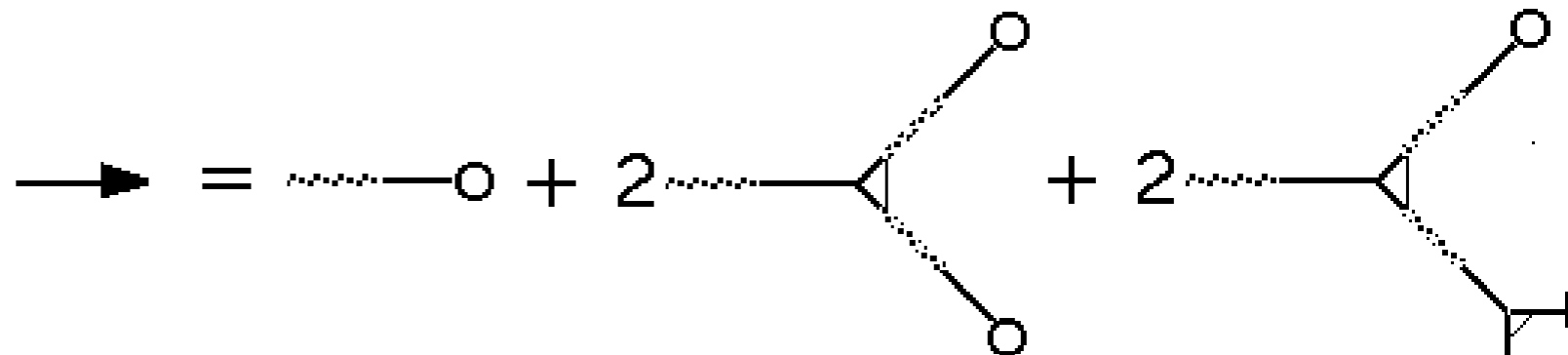
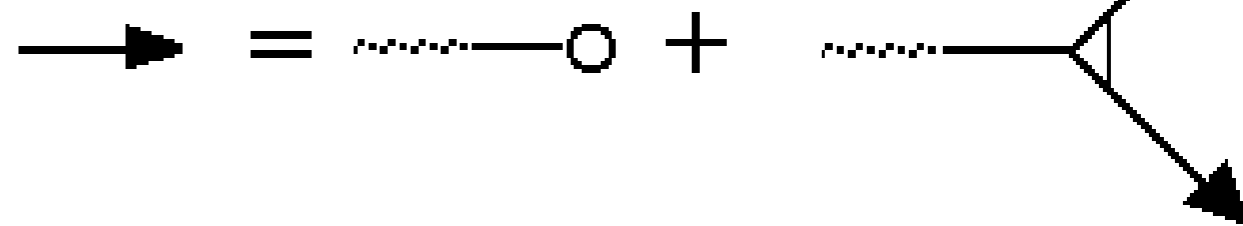
$$\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \underline{grad}(\underline{u}) = \underline{f} - \frac{1}{\rho} \underline{grad}(p) + \nu \Delta \underline{u}$$

 = $\underline{u}(\underline{x}, t)$

 = bare propagator

 = $\underline{f}(\underline{x}, t)$

 = vertex



Endless proliferation of higher and higher order diagrams ($Re \gg 1$)

Quasi-gaussian dead end

(a) $\langle uu \rangle = \langle ff \rangle \otimes \text{[diagram]} + 2 \text{[diagram]}$

(b) $\langle G \rangle = \text{[diagram]} + 4 \text{[diagram]}$

G_R renormalized propagator

(c) $\text{[diagram]} = \text{[diagram]} \otimes \text{[diagram]} + 2 \text{[diagram]} + 4 \text{[diagram]}$

(d) D.I.A.
 $\blacktriangleright = \triangleright + \text{[diagram]}$
 $P_R \quad P$

main assumption:

the forcing f is (quasi-) gaussian

however, the renormalization of the vertex

is non trivial and unsolved !

=> fundamental importance of

Fractionnaly Integrated Flux model (FIF, vector version)

FIF assumes that both the renomalized propagator G_R and force f_R are known:

$$G_R^{-1} * u = f_R$$

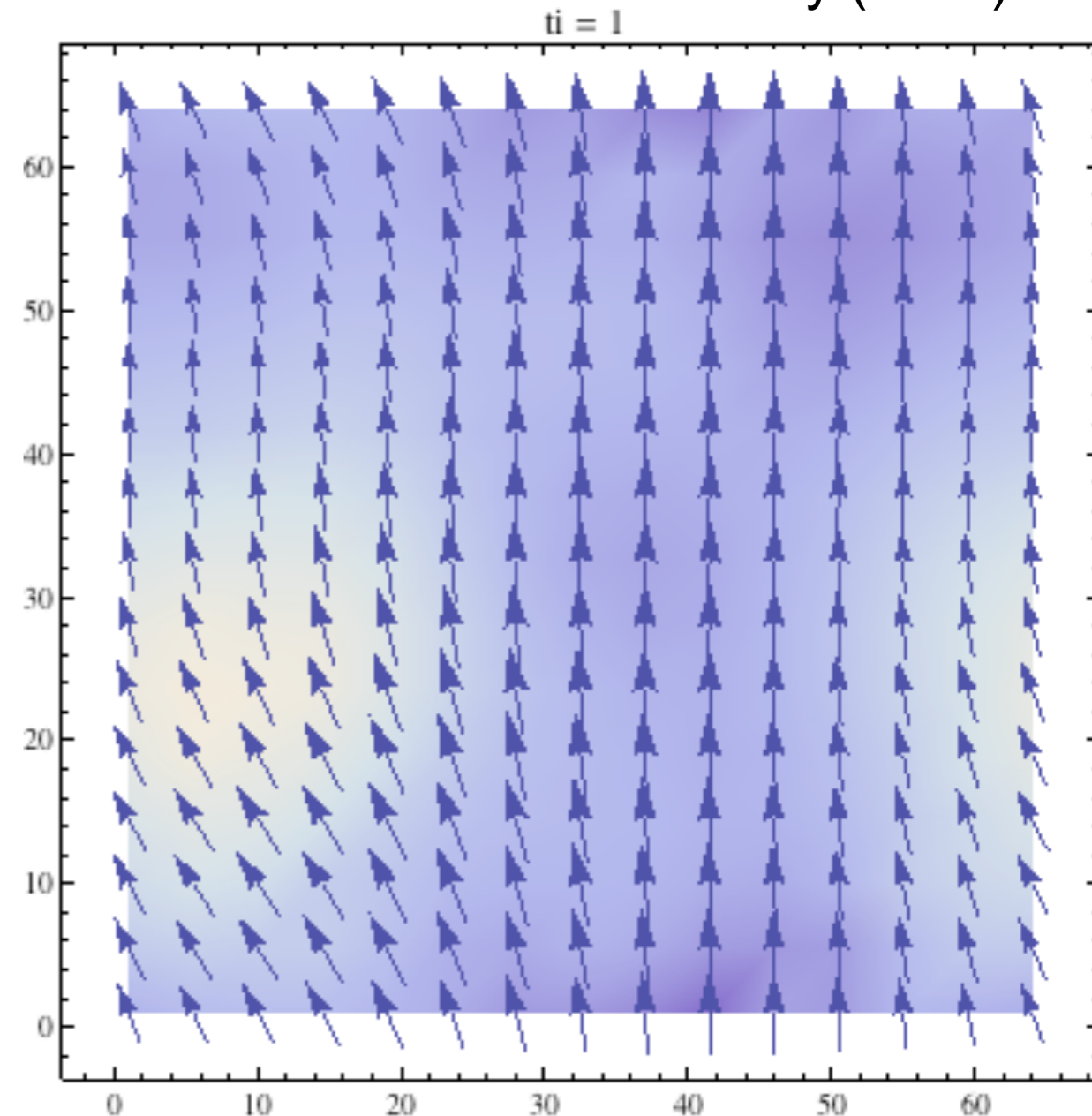
where:

$$f_R = \varepsilon^a$$

G_R^{-1} is a fractionnal differential operator

ε results from a continuous, vector, multiplicative cascade (Lie cascade)

Complex FIF simulation of a 2D cut of wind and its vorticity (color)



Fractionnaly Integrated Flux model (FIF, vector version)

FIF assumes that both the renomalized propagator G_R and force f_R are known:

$$G_R^{-1} * u = f_R$$

where:

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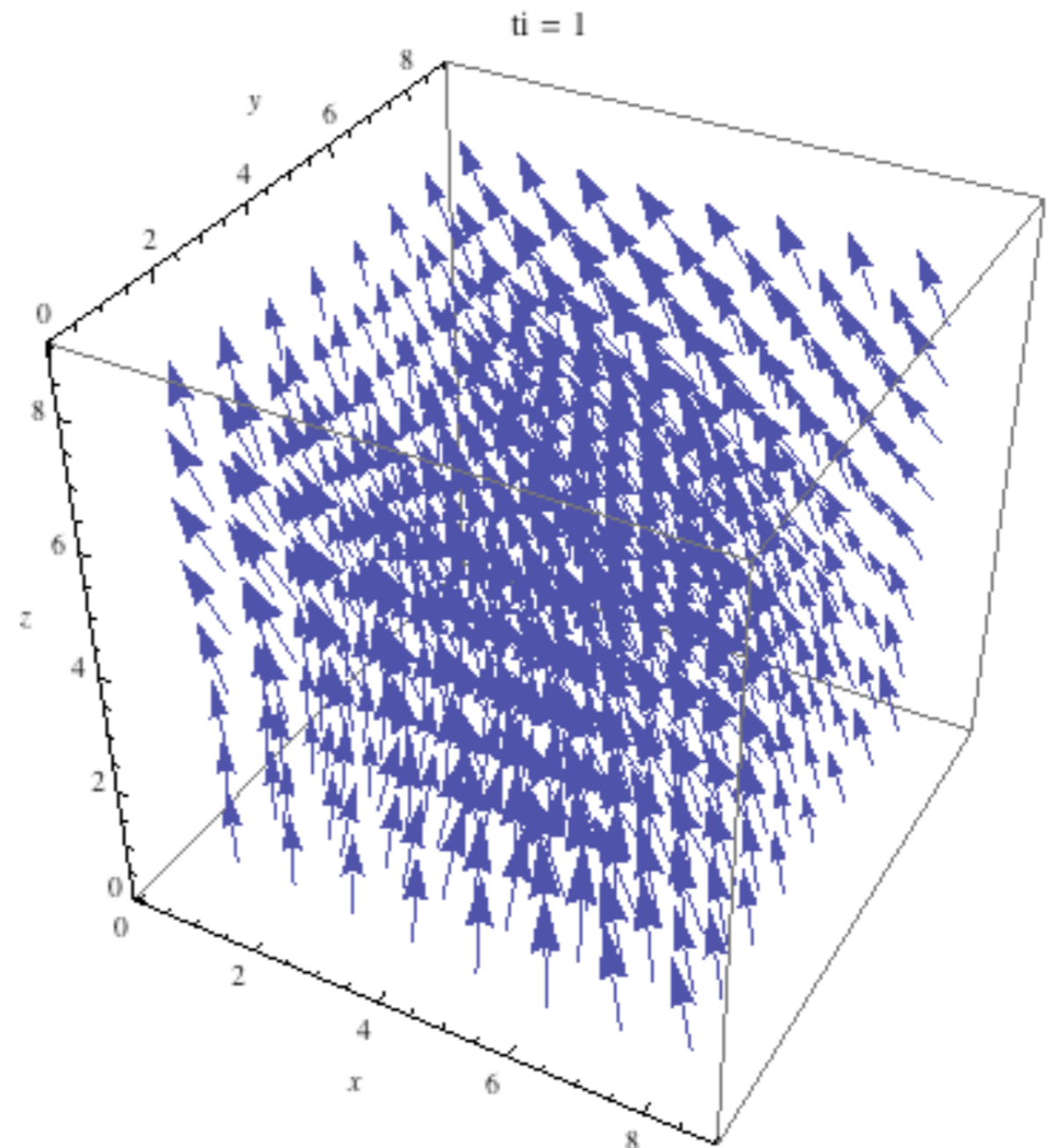
$$G_R^{-1}$$

is a fractionnal differential operator

$$\varepsilon$$

results from a continuous, vector, multiplicative cascade (Lie cascade)

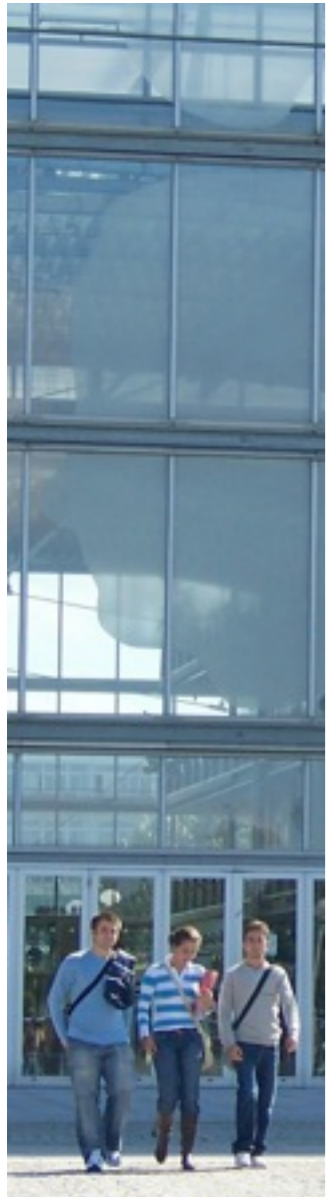
3D FIF wind simulation based on quaternions



Conclusions



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- Prediction in space-time complex systems is still at its infancy.
- Requires critical examination of concepts that emerged from the study of systems that are complex only in time (e.g. characteristic predictability time),
- space-time complex systems :
 - Relative space/time symmetry,
 - no characteristic times of predictability.
 - i.e. power-law decays of the predictability
 - higher predictability limits !

