A flexible hydrodynamic modelling framework for GPUs and CPUs: Application to urban flood events

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RainGain Intl. Workshop on Urban Pluvial Flood Modelling, Met Office, 6th October 2014

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Rationale

 Detailed catchment-scale modelling

Belford, Northumberland

- Natural flood management
- Barriers, pipes, hydrology...
- Tsunami propagation Japan/China
 - Multi-scale real-time warnings
- Broad-scale flood risk analyses
 London
 - Complex urban topography
 - Multi-source flood potential



Shallow flow models

• Godunov-type finite-volume scheme (Smith *et al.* 2014 in Urban Water Journal)

- Shock-capturing
- Stencil operations
- Directionally unsplit
- Second-order accuracy (Smith and Liang 2013 in Computers & Fluids)
 - MUSCL-Hancock
- Partial-inertial simplification (Bates *et al.* 2010 in J. Hydrology)
 - No Riemann solver required



History and Moore's 'law'

The CPU in 1997

- 8.8 million transistors
- \$469 at launch



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Multi-core transition

Stagnant clock speeds



Heterogeneous architectures



CPU

- Low-latency processor
- Low ratio of ALUs/control units
- Fast response times
- High RAM capacities
- General purpose computation



GPU... (APUs, Coprocessors, etc.)

- High-throughput processor
- High ratio of ALUs/control units
- Significant host-bus latency
- Limited DRAM capacities
- Challenges for optimisation

Graphics processing unit

CPU		High-grade GPUs	Compute Server
	inter re ^m i7		
Model: Inte	Xeon E5-2609	AMD FirePro V7800 (x2)	NVIDIA Tesla M2075 (x4)
Cost:	£311	£1,200	£8,400
SP GFLOPS:	Unknown	4032	5152
DP GFLOPS:	77	806	2064
Memory:	2GB (in price)	4GB (2GB x 2)	24GB (6GB x 4)
Cost/GFLOP	£4.04	£1.49	£4.07
DP multiplier/device: 1.0x		5.2x	6.7x

- Research platform
- Plug-in based software
 - Sediment transport
 - Discrete element modelling
- Visualisation in real-time
- Dynamic code generation
 - Cross-platform, crossarchitecture
 - Intel CPU, NVIDIA/AMD GPU, IBM Cell, Parallella, etc.







Smith LS, Liang Q (2013) Towards a generalised GPU/CPU shallow-flow modelling tool, Computers & Fluids, 88:334-343.





Why bother?





Simulation: 50 hours with FV SWEs 1st order



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- · Good match attainable at all resolutions tested
- Calibration only possible against known extent and river hydrometry
- Sensitivity varies significantly
 - Low velocity flows, flood defences overtopped
 - Expect high resolutions to give low floodplain sensitivity



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- High flow velocities and high sensitivity



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- 15:55 on 28 June 2012
- 50mm widely in 2 hours
- Severe transport disruption
 - Strategic transport routes
 - Blue light routes
 - Light rail services
 - National rail services

UK Met Office Operational NIMROD Rainfall Radar 28-Jun-2012 12:45 UTC



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UK Met Office Operational NIMROD Rainfall Radar 28-Jun-2012 13:35 UTC



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UK Met Office Operational NIMROD Rainfall Radar 28-Jun-2012 14:25 UTC



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UK Met Office Operational NIMROD Rainfall Radar 28-Jun-2012 15:15 UTC



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UK Met Office Operational NIMROD Rainfall Radar 28-Jun-2012 16:05 UTC



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UK Met Office Operational NIMROD Rainfall Radar 28-Jun-2012 16:55 UTC



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UK Met Office Operational NIMROD Rainfall Radar 28-Jun-2012 18:00 UTC



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Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 15:15 UTC



Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 15:30 UTC



Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 15:45 UTC



Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 16:00 UTC



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Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 16:30 UTC



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Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 17:45 UTC



Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 17:50 UTC



Newcastle upon Tyne Surface Water Model (Input from UKMO NIMROD) 28-Jun-2012 17:55 UTC



Modelling versus reality



Computational performance

- Simulation times for **3 hours** from start of the event
- 31km² area of central Newcastle
- Resolutions of **2m or better** are preferable

Resolution (cells)	1 x NVIDIA M2075 Released 2010		1 x NVIDIA K20 Released 2012	
4m (1,958,484)	00:45:21		00:31:18	0.69x
2m (7,833,169)	05:12:05	6.88x		

- Halve resolution, increase run-time approx. eight-fold
- Need to split work across multiple devices















- Wave propagation 1 cell / timestep
- Row synchronisation limited by half overlap

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timestep
• Row synchronisation
limited by half overlap

$$\Delta t_{D1} = \min\left(\frac{\Delta x}{u + \sqrt{gh}}, \frac{\Delta y}{v + \sqrt{gh}}\right)$$

$$\Delta t = \min\left(\Delta t_{D1}, \Delta t_{D2}\right)$$

• Wave propagation 1 cell /
timestep
• Row synchronisation
limited by half overlap

$$\Delta t_{D1} = \min\left(\frac{\Delta x}{u + \sqrt{gh}}, \frac{\Delta y}{v + \sqrt{gh}}\right)$$
• Can be overcome by
forecasting likely
timesteps
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forecasting likely
timesteps
• May require reversing a
simulation

Computational performance

- Domain decomposed across four devices
- Current servers are limited to **eight** PCI-e x16 slots
- Explicit timestep synchronisation or domain-independent timesteps
- Best performance scaling on large domains (ratio of sync:work)

Synchronisation	Overlap Resolution (cells)		Devices	Devices NVIDIA Tesla M2075		
None	N/A	2m (7,833,169)	1 x	05:12:05	1.00x	
Every 1 iteration	10 cells	2m (8,035,336)	4 x	01:41:11	/3.08	
Every 50 iterations	50 cells	2m (8,805,496)	4 x	01:28:31	/3.52	

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Independent domains only synchronise every 3 seconds

Conclusions

- Supercomputer hydraulics feasible
 - Potentially costly
 - Need software rewrite
- Run-times will decrease for multi-core/heterogeneous softwares
- Work division is challenging
 - Scaling vs. overheads
 - Minimising communication
 - Forecasting timesteps

